

4.2 Directional Derivative

For a function of 2 variables $f(x, y)$, we have seen that the function can be used to represent the surface

$$z = f(x, y)$$

and recall the geometric interpretation of the partials:

- (i) $f_x(a, b)$ -represents the rate of change of the function $f(x, y)$ as we vary x and hold $y = b$ fixed.
- (ii) $f_y(a, b)$ -represents the rate of change of the function $f(x, y)$ as we vary y and hold $x = a$ fixed.

We now ask, at a point P can we calculate the slope of f in an arbitrary direction?

Recall the definition of the vector function ∇f ,

$$\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right).$$

We observe that,

$$\begin{aligned}\nabla f \cdot \hat{i} &= f_x \\ \nabla f \cdot \hat{j} &= f_y\end{aligned}$$

This enables us to calculate the directional derivative in an arbitrary direction, by taking the dot product of ∇f with a unit vector, \vec{u} , in the desired direction.

DEFINITION. *The directional derivative of the function f in the direction \vec{u} denoted by $D_{\vec{u}}f$, is defined to be,*

$$D_{\vec{u}}f = \frac{\nabla f \cdot \vec{u}}{|\vec{u}|}$$

EXAMPLE. What is the directional derivative of $f(x, y) = x^2 + xy$, in the direction $\vec{i} + 2\vec{j}$ at the point $(1, 1)$?

SOLUTION: We first find ∇f .

$$\begin{aligned}\nabla f &= \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) \\ &= (2x + y, x) \\ \nabla f(1, 1) &= (3, 1)\end{aligned}$$

Let $u = \vec{i} + 2\vec{j}$.

$$|\vec{u}| = \sqrt{1^2 + 2^2} = \sqrt{1 + 4} = \sqrt{5}.$$

$$\begin{aligned}D_{\vec{u}}f(1, 1) &= \frac{\nabla f \cdot \vec{u}}{|\vec{u}|} \\ &= \frac{(3, 1) \cdot (1, 2)}{\sqrt{5}} \\ &= \frac{(3)(1) + (1)(2)}{\sqrt{5}} \\ &= \frac{5}{\sqrt{5}} \\ &= \sqrt{5}\end{aligned}$$

Properties of the Gradient deduced from the formula of Directional Derivatives

$$\begin{aligned}D_{\vec{u}}f &= \frac{\nabla f \cdot \vec{u}}{|\vec{u}|} \\ &= \frac{|\nabla f| |\vec{u}| \cos \theta}{|\vec{u}|} \\ &= |\nabla f| \cos \theta\end{aligned}$$

1. If $\theta = 0$, i.e. \vec{u} points in the same direction as ∇f , then $D_{\vec{u}}f$ is maximum. Therefore we may conclude that
 - (i) ∇f points in the steepest direction.
 - (ii) The magnitude of ∇f gives the slope in the steepest direction.

2. At any point P , $\nabla f(P)$ is **perpendicular to the level set** through that point.

EXAMPLE. 1. Let $f(x, y) = x^2 + y^2$ and let $P = (1, 2, 5)$. Then P lies on the graph of f since $f(1, 2) = 5$. Find the slope and the direction of the steepest ascent at P on the graph of f

SOLUTION: • We use the first property of the Gradient vector. The direction of the steepest ascent at P on the graph of f is the direction of the gradient vector at the point $(1, 2)$.

$$\begin{aligned}\nabla f &= \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) \\ &= (2x, 2y) \\ \nabla f(1, 2) &= (2, 4).\end{aligned}$$

- The slope of the steepest ascent at P on the graph of f is the magnitude of the gradient vector at the point $(1, 2)$.

$$|\nabla f(1, 2)| = \sqrt{2^2 + 4^2} = \sqrt{20}.$$

2. Find a normal vector to the graph of the equation $f(x, y) = x^2 + y^2$ at the point $(1, 2, 5)$. Hence write an equation for the tangent plane at the point $(1, 2, 5)$.

SOLUTION: We use the second property of the gradient vector. For a function g , $\nabla g(P)$ is **perpendicular to the level set**. So we want our surface $z = x^2 + y^2$ to be the level set of a function.

Therefore we define a new function,

$$g(x, y, z) = x^2 + y^2 - z.$$

Then our surface is the level set

$$\begin{aligned}g(x, y, z) &= 0 \\ x^2 + y^2 - z &= 0 \\ z &= x^2 + y^2\end{aligned}$$

$$\begin{aligned}
\nabla g &= \left(\frac{\partial g}{\partial x}, \frac{\partial g}{\partial y}, \frac{\partial g}{\partial z} \right) \\
&= (2x, 2y, -1) \\
\nabla g(1, 2, 5) &= (2, 4, -1)
\end{aligned}$$

By the above property, $\nabla g(P)$ is perpendicular to the level set $g(x, y, z) = 0$. Therefore $\nabla g(P)$ is the required normal vector.

Finally an equation for the tangent plane at the point $(1, 2, 5)$ on the surface is given by

$$2(x - 1) + 4(y - 2) - 1(z - 5) = 0.$$

4.3 Curl and Divergence

We denoted the gradient of a scalar function $f(x, y, z)$ as

$$\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$$

Let us separate or isolate the operator $\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$. We can then define various physical quantities such as div, curl by specifying the action of the operator ∇ .

Divergence

DEFINITION. Given a vector field $\vec{v}(x, y, z) = (v_1(x, y, z), v_2(x, y, z), v_3(x, y, z))$, the divergence of \vec{v} is a scalar function defined as the dot product of the vector operator ∇ and \vec{v} ,

$$\begin{aligned}
\text{Div } \vec{v} &= \nabla \cdot \vec{v} \\
&= \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot (v_1, v_2, v_3) \\
&= \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z}
\end{aligned}$$

EXAMPLE. Compute the divergence of $(x - y)\vec{i} + (x + y)\vec{j} + z\vec{k}$.

SOLUTION:

$$\begin{aligned}\vec{v} &= ((x - y), (x + y), z) \\ \nabla &= \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \\ \text{Div } \vec{v} &= \nabla \cdot \vec{v} \\ &= \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot ((x - y), (x + y), z) \\ &= \frac{\partial(x - y)}{\partial x} + \frac{\partial(x + y)}{\partial y} + \frac{\partial z}{\partial z} \\ &= 1 + 1 + 1 \\ &= 3\end{aligned}$$

Curl

DEFINITION. The curl of a vector field is a vector function defined as the cross product of the vector operator ∇ and \vec{v} ,

$$\begin{aligned}\text{Curl } \vec{v} = \nabla \times \vec{v} &= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix} \\ &= \left(\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right) i - \left(\frac{\partial v_3}{\partial x} - \frac{\partial v_1}{\partial z} \right) j + \left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right) k\end{aligned}$$

EXAMPLE. Compute the curl of the vector function $(x - y)\vec{i} + (x + y)\vec{j} + z\vec{k}$.

SOLUTION:

$$\begin{aligned}\text{Curl } \vec{v} = \nabla \times \vec{v} &= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (x - y) & (x + y) & z \end{vmatrix} \\ &= \left(\frac{\partial z}{\partial y} - \frac{\partial(x + y)}{\partial z} \right) i - \left(\frac{\partial z}{\partial x} - \frac{\partial(x - y)}{\partial z} \right) j + \left(\frac{\partial(x + y)}{\partial x} - \frac{\partial(x - y)}{\partial y} \right) k \\ &= (0 - 0)\vec{i} - (0 - 0)\vec{j} + (1 - (-1))\vec{k} \\ &= 2\vec{k}\end{aligned}$$

4.4 Laplacian

We have seen above that given a vector function, we can calculate the divergence and curl of that function. A scalar function f has a vector function ∇f associated to it. We now look at $\text{Curl}(\nabla f)$ and $\text{Div}(\nabla f)$.

$$\begin{aligned}\text{Curl}(\nabla f) &= \nabla \times \nabla f \\ &= \left(\frac{\partial f_z}{\partial y} - \frac{\partial f_y}{\partial z}\right)i + \left(\frac{\partial f_x}{\partial z} - \frac{\partial f_z}{\partial x}\right)j + \left(\frac{\partial f_y}{\partial x} - \frac{\partial f_x}{\partial y}\right)k \\ &= (f_{yz} - f_{zy})i + (f_{zx} - f_{xz})j + (f_{xy} - f_{yx})k \\ &= 0 \\ \text{Div}(\nabla f) &= \nabla \cdot \nabla f \\ &= \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right) \cdot \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}\right) \\ &= \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}\end{aligned}$$

DEFINITION. The Laplacian of a scalar function $f(x, y)$ of two variables is defined to be $\text{Div}(\nabla f)$ and is denoted by $\nabla^2 f$,

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}.$$

The Laplacian of a scalar function $f(x, y, z)$ of three variables is defined to be $\text{Div}(\nabla f)$ and is denoted by $\nabla^2 f$,

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}.$$

EXAMPLE. Compute the Laplacian of $f(x, y, z) = x^2 + y^2 + z^2$.

SOLUTION:

$$\begin{aligned}\nabla^2 f &= \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} \\ &= \frac{\partial 2x}{\partial x} + \frac{\partial 2y}{\partial y} + \frac{\partial 2z}{\partial z} \\ &= 2 + 2 + 2 \\ &= 6.\end{aligned}$$

We have the following identities for the Laplacian in different coordinate systems:

$$\text{Rectangular} : \nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

$$\text{Polar} : \nabla^2 f = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$$

$$\text{Cylindrical} : \nabla^2 f = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial^2 f}{\partial z^2}$$

$$\text{Spherical} : \nabla^2 f = \frac{1}{\rho^2} \frac{\partial}{\partial \rho} \left(\rho^2 \frac{\partial f}{\partial \rho} \right) + \frac{1}{\rho^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{\rho^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}$$

EXAMPLE. Consider the same function $f(x, y, z) = x^2 + y^2 + z^2$. We have seen that in rectangular coordinates we get

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = 6.$$

We now calculate this in cylindrical and spherical coordinate systems, using the formulas given above.

1. Cylindrical Coordinates.

We have $x = r \cos \theta$ and $y = r \sin \theta$ so

$$f(r, \theta, z) = r^2 \cos^2 \theta + r^2 \sin^2 \theta + z^2 = r^2 + z^2.$$

Using the above formula:

$$\begin{aligned} \nabla^2 f &= \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial^2 f}{\partial z^2} \\ &= \frac{1}{r} \frac{\partial}{\partial r} (r2r) + 0 + \frac{\partial(2z)}{\partial z} \\ &= \frac{1}{r} (4r) + 2 \\ &= 4 + 2 \\ &= 6 \end{aligned}$$

2. Spherical Coordinates.

We have $x = \rho \sin \phi \cos \theta$, $y = \rho \sin \phi \sin \theta$, $z = \rho \cos \phi$ and $\rho = \sqrt{x^2 + y^2 + z^2}$, so

$$f(r, \theta, z) = \rho^2.$$

Using the above formula:

$$\begin{aligned}\nabla^2 f &= \frac{1}{\rho^2} \frac{\partial}{\partial \rho} \left(\rho^2 \frac{\partial f}{\partial \rho} \right) + \frac{1}{\rho^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{\rho^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2} \\ &= \frac{1}{\rho^2} \frac{\partial}{\partial \rho} (\rho^2 2\rho) + 0 + 0 \\ &= \frac{1}{\rho^2} \frac{\partial}{\partial \rho} (2\rho^3) \\ &= \frac{1}{\rho^2} (6\rho^2) \\ &= 6.\end{aligned}$$

These three different calculations all produce the same result because ∇^2 is a derivative with a real physical meaning, and does not depend on the coordinate system being used.

References

1. A brilliant animated example, showing that the maximum slope at a point occurs in the direction of the gradient vector. The animation shows:
 - a surface
 - a unit vector rotating about the point $(1, 1, 0)$, (shown as a rotating black arrow at the base of the figure)
 - a rotating plane parallel to the unit vector, (shown as a grey grid)
 - the traces of the planes in the surface, (shown as a black curve on the surface)
 - the tangent lines to the traces at $(1, 1, f(1, 1))$, (shown as a blue line)
 - the gradient vector (shown in green at the base of the figure)

<http://archives.math.utk.edu/ICTCM/VOL10/C009/dd.gif>

2. A complete set of notes on Pre-Calculus, Single Variable Calculus, Multi-variable Calculus and Linear Algebra.

Here is a link to the chapter on Directional Derivatives.

<http://tutorial.math.lamar.edu/Classes/CalcIII/DirectionalDeriv.aspx>.

Here is a link to the chapter on Curl and Divergence.

<http://tutorial.math.lamar.edu/Classes/CalcIII/CurlDivergence.aspx>