## UiO: Institutt for informatikk

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IN3160, IN4160
Introduction to VHDL Basic layout for VHDL

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## Messages:

- Assignment 2 is revised
- Please re-load from canvas.
- Do try program the boards on LISP.
- Report problems to lab supervisors.
- Please select a LISP machine, by writing your user name on https://docs.google.com/spreadsheets/d/1Xyr6HJnZzmHxpaLTAED MDBz0qIXPJdZMPbqneaP4CLg/edit\#gid=0
- Please negotiate timeslots with your fellow students sharing machine


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## Course Goals and Learning Outcome

## https://www.uio.no/studier/emner/matnat/ifi/IN3160/index-eng.html

In this course you will learn about the design of advanced digital systems. This includes programmable logic circuits, a hardware design language and system-on-chip design (processor, memory and logic on a chip). Lab assignments provide practical experience in how real design can be made.

After completion of the course you will:

- understand important principles for design and testing of digital systems
- understand the relationship between behavior and different construction criteria
- be able to describe advanced digital systems at different levels of detail
- be able to perform simulation and synthesis of digital systems.


## Goals for this lesson:

- Know the basic structure of VHDL
- Know which design entities there are
- Know how assignment and statements works
- Know the basic functionality of processes
- Be able to create designs using VHDL
- Know the relation between phsyical signals and their declaration.
- Know the difference between basic coding styles
- Know basic layout principles
- Guidelines for capital letters
- Basic layout types
- Principles for indentation, commenting, naming, punctuations


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## Overview

- Repetition
- VHDL Structure
- Design entities
- Signals, variables, vectors
- Processes
- Libraries
- STD_LOGIC
- Operators
- String literals
- Code layout principles
- Next lesson: Combinational logic
- Assignments and suggested reading for this week


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## HDL

- VHDL = VHSIC HDL:
- Very High Speed Integrated Circuit Hardware Description Language
- The purpose is to generate hardware, and verify it through simulation.
- Synthesizable (realizable) code work concurrently (in parallel).
- Code for simulation include things such as file I/O which cannot be synthesized.
- Testbenches can and will use some synthesizable elements, but will in general look more like other sequential languages, and use sequential statements. This may be confusing at times...
- VHDL does come with several libraries.

Code for generating and parsing simulation data (Test benches)


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## HDL vs software



| HDL «Hardware description <br> language» | Software programs |
| :--- | :--- |
| Defines the logic function of a circuit | Defines the sequence of instructions <br> and which data shall be used for one or <br> more processors or processor cores |
| CAD tools syntetizises designs to <br> enable realization using physical gates. | A compiler translates program code to <br> machine code instructions that the <br> processor can read sequentially from <br> memory |
| Implemented using programmable <br> logic (PL, FPGA, CPLD, PLD, PAL, PLA, ...) <br> or ASICs (application specific circuits) <br> ("ASICs", processors, ..-chips,.. etc.) | Is stored in computer memory |
| Verilog (SystemVerilog) <br> VHDL (VHDL 2008) | C, C++, C\#, Python, Java, assemblere <br> (ARM, MIPS, x86, ...) Fortran, LISP, |
| (System c m. fl.) | Simula, Pascal, osv... |

int sum(int a, int b) \{
int s;
$\mathrm{s}=\mathrm{a}+\mathrm{b} ;$
return s ;
nov R5, \#0
;set base adr \#8] , se LDR R8, [R5, \#12]; load reg R8 ADD R0, R7, R8 ; R0=R7+R8 STR R0, [R5, \#16];store R0

01001100100110010010010001001010 11001100101110010110010011110110 1001100100110010010010001011010
(binary code is random, for illustration only)

C, C++, C\#, Python, Java, assemblere (ARM, MIPS, x86, ...) Fortran, LISP, Simula, Pascal, osv...

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## VHDL structure

- Design entities
- Architecture styles
- Ports and signals
- Vectors
- Assignment
- Libraries
- STD_LOGIC data type
- Operators

- Small design files will normally contain both entity and an architecture
- In larger designs these may be separated, several architectures can be used for one entity.
- Details will be revealed later..




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## VHDL Design entities overview $\mathbf{2 / 2}$

- VHDL uses and can be used to create packages
- We will almost always use packages in precompiled libraries.
- Configuration files can be used to specify which components or architectures that shall be used in (large) designs
- (Not a primary concern for in3160)

Declares everything that should be publicly available in the package

Declarations

- Declaration of all that should be visible
outside the package
Components
- other design entities that are used as a part of an architecture


Subprograms
Subprograms

- Instantiable code that provide a value or


Type declarations
Constants

## Configuration

Defines links between modules, such as which architectures shall be linked to which entities in a design with multiple architectures for an entity.

Using a configuration file for this can be useful for large designs, for example by switching thoroughly tested components with logical models to simulate faster

Configuration statements can also be used directly in declarative regions of each design unit, utilizing the 'use' clause

## Constants for local use

## Subprograms

- Instantiable code that provide a value or perform one or more tasks



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## VHDL Entity and Architecture

- Entity defines Input and Output ports in the design

- There is only one entity in a vhdl file..
- Architecture defines what the design does.
- There can be several architectures for an entity
- Architectures, may be defined using different styles (next slide)
- "RTL" and "Dataflow" are just names providing information; changing these names would not change function.

library IEEE; use IEEE.STD_LOGIC_1164.all;

```
entity D_flipflop is
    port(
        clk: in std_logic;
        D : in std_logic;
        Q : out std_logic
    );
end entity D_FLIPFLOP;
architecture RTL of D_flipflop is
begin
    process (clk) is
    begin
        if rising_edge(clk) then
            Q <= 'D';
        end if;
    end process;
end architecture RTL;
```

architecture data_flow of $D_{-} f l i p f l o p ~ i s$ signal e, f, g, h, i, j, k, l: std_logic; begin
-- concurrent statements
e <= NOT (D AND clk);
f <= NOT (e AND clk);
$\mathrm{g}<=$ NOT (e AND h);
$h<=$ NOT (f AND $g$ );
i <= NOT (g AND NOT clk);
j <= NOT (h AND NOT clk);
$\mathrm{k}<=$ NOT (l AND i);
l <= NOT (k AND j);
$\mathrm{Q}<=\mathrm{k}$;

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## 4 styles of architecture modeling

library IEEE

use IEEE.STD_LOGIC_1164.all;
entity D_flipflop is
port (
clk: in std_logic;
D: in std_logic;
Q: out std_logic
);
end entity D_flipflop;
architecture RTL of D_flipflop is begin
process (clk) is
begin
if rising_edge(clk) then
Q <= 'D';
end if;
end process;
end architecture RTL;
architecture data_flow of D_flipflop is
signal e, f, g, h, i, j, $\bar{k}, \mathrm{l}: ~ s t d \_l o g i c ;$ begin
-- concurrent statements
e <= not (D and clk);
$\mathrm{f}<=\operatorname{not}(\mathrm{e}$ and clk$)$;
$\mathrm{g}<=\operatorname{not}(\mathrm{e}$ and h$)$;
$h$ <= not ( $f$ and $g$ );
i <= not (g and not clk);
$j<=$ not ( $h$ and not clk);
$\mathrm{k}<=\operatorname{not}$ (l and i);
$1<=\operatorname{not}(k$ and $j)$;
Q <= k;
end architecture data_flow

RTL, register transfer level

- easy to read
- describes registers and what happens between them
- «default» for sequential logic


## Data Flow

- typically used for simple concurrent statements
- will easily become unreadable if used extensively.
library IEEE;
use IEEE.STD_LOGIC_1164.all;
entity my_thing is
port (
B: in std_logic_vector(5 downto 0);
C, D, E, F: in std_logic;
G: out std_logic;
H: out std_logic_vector (64 downto 0);
I: out std_logic
);
end entity my_thing;


## Structural

- Ties components together
- Typically used in test benches, and when using predefined components

architecture structural of my_thing is signal js: std_logic;
signal ks: std_logic_vector(64 downto 0) signal ls: std_logic;
component apple is
A: in std logic;
B: in std_logic_vector(5 downto 0),
C: out std_logic;
D: out std_logic_vector (64 downto 0)
);
componet


## port (

A, B, C: in std_logic;
D, E: out std_logic
);
end component;
component banana is
port (
smurf: in std_logic_vector(64 downto 0 ); cat, dog, donkey: in std_logic;
horse: out std_logic;
monkey: out std_llogic_vector(64 downto 0)
end ;
end component;
begin -- port map (component => My_thing)
U1: apple port map(
A => A,
$B \Rightarrow B$,
C => js
D $\Rightarrow$ ks
);
U2: pear port map(
$A \Rightarrow D$,
$B \Rightarrow E$,

$\mathrm{D} \Rightarrow \mathrm{l}$ ls
$\mathrm{E} \Rightarrow \mathrm{I}$
);
U3: banana port map(
smurf $\Rightarrow$ ks,
cat $\Rightarrow$ js,
dog $\Rightarrow$ C,
donkey $\Rightarrow>1 s$,
horse $\Rightarrow$ G,
monkey $\Rightarrow \mathrm{H}$
);
end architecture structural;

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## Ports and signals

- Ports define the entity interface
- IN:
- can only drive
- cannot read or be assigned to a signal
- OUT:
- signals can only be driven
- They should be assigned in the architecture (In VHDL 2008, output ports can be read as an internal signal).
- INOUT
- Can be both driven and read (typical use is for buses)
- Signals are internal
- For connecting internal modules, subprograms and processes.


```
library IEEE;
use IEEE.STD_LOGIC_1164.ALL;
entity My_thing is
    port(
        Ain : in STD LOGIC;
        Binout : inout STD_LOGIC;
        Cout : out STD_LOGIC);
end entity My_thing;
architecture DataFlow of My_thing is
    signal s1, s2, s3, s4 : STD_LOGIC;
begin
    -- ...
    -- concurrent statements
    s1 <= Ain; -- IN can only drive
    s2 <= Binout; -- INOUT *can* be driven
    Binout <= s3; -- INOUT *can* drive
    Cout <= s4; -- OUT can only be driven
end architecture DataFlow;
```


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## Ports continued

INOUT is for tying input and output to the same pin

- should implement tristate functionality.
- ' $Z$ ' means it is not driven (tristate)
- Typically to be used when connecting a bus that can have multiple drivers.


## DO NOT use INOUT for convenience!

- The compiler will not alert you if you are driving from two sources simultaneously.
- May cause electrical faults
- INOUT may infer inferior structures (long delays)
- 

use an extra signal unless you need to assign both input and output to the same physical location.


```
library IEEE;
use IEEE.STD_LOGIC_1164.ALL;
entity My_thing is
    port(
        Ain : in STD_LOGIC;
        Binout : inout STD_LOGIC;
        Cout : out STD_LOGIC);
end entity My_thing;
architecture DataFlow of My_thing is
    signal s1, s2, s3, s4 : STD_LOGIC;
begin
    -- ...
    -- concurrent statements
    s1 <= Ain; -- IN can only drive
    s2 <= Binout; -- INOUT *can* be driven
    Binout <= s3; -- INOUT *can* drive
    Cout <= s4; -- OUT can only be driven
end architecture DataFlow;
```


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## Type «Vectors»

- signal my_sig std_logic;

- signal my_vec std_logic_vector(3 downto 0);



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## Signals and variables

- Signals are for inter-architecture communication
- Between processes, modules and subprograms
- Variables are subprogram(or process)-internal
- To make code clearer, and more local.
- Example note:
- placement of s\&v declarations
- Signal assignment order is irrelevant outside processes

```
architecture example of sigvar is
    -- (signal) declarations
    signal S, T : std_logic;
begin
    -- statements
    S <= A and B;
    process (A,B) is
        -- (variable) declarations
        variable V : std_logic;
    begin
        -- process body
        V := '0';
        -- ..
    end process;
    X <= S XOR T;
end architecture;
```


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## Signal and variable assignment

- Signals can be used concurrently
- both in and outside processes
- Signals are assigned using <=
- Signals uses event based updates
- ie after a process is complete.
- Variables can only be used inside processes and subprograms
- Variables are assigned using :=
- Variables are updated immediately in simulation
- Processes can have variables store values
- Initialized at the beginning of simulation
- Subprograms (procedure, function) can not have variables store values
- initialized on every call

```
D(6 downto 0) <= E(3 downto 1) & (others => '0');
```

D(6 downto 0) <= E(3 downto 1) \& (others => '0');
-- D is a vector having 7 input signals
-- D is a vector having 7 input signals
-- D(6) <= E(3)
-- D(6) <= E(3)
-- D(5) <= E(2)
-- D(5) <= E(2)
-- D(4) <= E(1)
-- D(4) <= E(1)
-- D(3 downto 0) <= "0000"

```
    -- D(3 downto 0) <= "0000"
```

```
A <= B; -- A reads B, or A is assigned to B's ouput,
```

A <= B; -- A reads B, or A is assigned to B's ouput,
-- (A is a signal)
-- (A is a signal)
C := B; -- C is given B's value, C is a variable
C := B; -- C is given B's value, C is a variable
C := B; -- C is given B's value, C is a variable
-- variables are used internally in processes.

```
    -- variables are used internally in processes.
```

    -- variables are used internally in processes.
    ```

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\section*{Processes}
- A process is one (concurrent) statement
- Ensures one driver for each signal by using priority.

\section*{Processes}
- signal assignment using sequentially ordered statements

\section*{Sensitivity list}
- a list that tells the compiler which signals that may trigger events in the process

Declarations
For local use
- The process body has sequential priority
- Last assignment takes precedence over previous.
- Variables can be assigned multiple times within a process body(!)
- sensitivity list
- determines when the process body is invoked during simulation
- Event triggered
- Can be used to make sequential logic
- Clocked events infers flipflops (or latches)

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\section*{Process example}
```

library IEEE;
use IEEE.std_logic_1164.all;
entity sigvar is
port(
A, B : in std_logic;
X : out std_logic
);
end entity sigvar;

```
```

architecture example of sigvar is
-- declarations
signal S, T : std_logic;
begin
-- statements
S <= A and B;
process (A,B) is
-- decalarations
variable V : std_logic;
begin
-- process body
V := '0';
if (A = '1') then
V := '1'
end if;
if (B = '1') then
V:= '1';
end if;
T <= V;
end process;
X <= S XOR T;
end architecture;

```

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\section*{Libraries and Data types}
- VHDL is built upon use of libraries and packages.
- You can both use existing ones, and create your own.
- Most used is the IEEE library, which contains
- The built-in standard (std) package, containing:
- bit, integer, natural, positive, boolean, string, character, real, time, delay_length
- std_logic_1164 (which defines the STD_LOGIC type)
- numeric_std (numeric operations for std_logic_vectors)
- std_logic_textio (to provide IO during simulation)
- numeric_bit (numeric operations for bit vectors)
- etc.

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\section*{STD_LOGIC TYPE (requires std_logic_1164 package from IEEE library)}
- STD_LOGIC is a type that has the following possible values
- 'U’ Uninitialized (Typically seen in simulation before initializing values)
- ' \(X\) ' Unknown (typically when a signal is driven to both 0 and 1 simultaneously)
- '0’ Driven low
- '1' Driven High
- 'Z’ Tristate
- 'W' Weak unknown (when driven by two different weak drivers)
- 'L’ Weak '0’ (Typically for simulating a pulldown resistor)
- 'H' Weak '1' (Typically for simulating a pullup resistor)
- ' - D Don't care (Typically for assessing results in simulator).
- You will only assign (synthesizable) signals to ' 0 ', 1 ' and ' \(Z\) '
- Type STD_LOGIC_VECTOR is array (NATURAL range <>) og STD_LOGIC
- STD logic vector is used for hardware. For simulation, other types (such as integer) may be faster. Thus we use STD_LOGIC for hardware interactions, and other types when possible for test bench code.

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\section*{std_logic -- values}

\begin{tabular}{|c|l|l|}
\hline Value & Name & Usage \\
\hline 'U' & Uninitialized state & Used as a default value \\
\hline ' \(X\) ' & Forcing unknown & Bus contentions, error conditions, etc. \\
\hline '0' & Forcing zero & Transistor driven to GND \\
\hline '1' & Forcing one & Transistor driven to VCC \\
\hline 'Z' & High impedance & 3-state buffer outputs \\
\hline 'W' & Weak unknown & Bus terminators \\
\hline 'L' & Weak zero & Pull down resistors \\
\hline 'H' & Weak one & Pull up resistors \\
\hline '_' & Don't care & Used for synthesis and advanced modeling \\
\hline
\end{tabular}


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\section*{-- multiple drivers signal c : std_logic;}

\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|}
\hline Signal A/B & 'U' & 'X' & '0' & '1' & 'Z' & 'W' & 'L' & 'H' & '-' \\
\hline 'U' & 'U' & 'U' & 'U' & 'U' & 'U' & 'U' & 'U' & 'U' & 'U' \\
\hline 'X' & 'U' & 'X' & 'X' & 'X' & 'X' & 'X' & 'X' & 'X' & 'X' \\
\hline '0' & 'U' & 'X' & '0' & 'X' & '0' & '0' & '0' & '0' & 'X' \\
\hline '1' & 'U' & 'X' & 'X' & '1' & '1' & '1' & '1' & '1' & 'X' \\
\hline 'Z' & 'U' & 'X' & '0' & '1' & 'Z' & 'W' & 'L' & 'H' & 'X' \\
\hline 'W' & 'U' & 'X' & '0' & '1' & 'W' & 'W' & 'W' & 'W' & 'X' \\
\hline 'L' & 'U' & 'X' & '0' & '1' & 'L' & 'W' & 'L' & 'W' & 'X' \\
\hline 'H' & 'U' & 'X' & '0' & '1' & 'H' & 'W' & 'W' & 'H' & 'X' \\
\hline '-' & 'U' & 'X' & 'X' & 'X' & 'X' & 'X' & 'X' & 'X' & 'X' \\
\hline
\end{tabular}

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\section*{Tri-state buffer}
- Hardware can only read '0' or '1'
```

A <= B when EN = '1' else 'Z';
-- ekvivalent med
TRISTATE:
process (B,EN)
begin
if EN = '1' then
A<= B;
else
A<= 'Z';
end if;
end process;

```

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\section*{VHDL operator priority}
- Functions are interpreted from left to right (in reading order).
- Use paranthesis to govern priority!
\begin{tabular}{|c|c|c|}
\hline Prioritet & Operator klasse & Operatorer \\
\hline 1 (first) & miscellaneous & **, abs, not \\
\hline 2 & multiplying & *, /, mod, rem \\
\hline 3 & sign & +, - \\
\hline 4 & adding & +, -, \& \\
\hline 5 & Shift & \[
\begin{aligned}
& \text { sll, srl, sla, sra, } \\
& \text { rol, ror }
\end{aligned}
\] \\
\hline 6 & relational & \[
\begin{aligned}
& =, /=,<,<=,>,>=, ?= \\
& ? /=, ?<, ?<=, ?>, ?>=
\end{aligned}
\] \\
\hline 7 & logical & And, or, nand, nor, xor, xnor \\
\hline 8 (last) & condition & ? ? \\
\hline
\end{tabular}

Examples (elaboration on next page):
a <= a or b and c ; == a <= ( a or b ) and c ;
\(\mathrm{z}<=\mathrm{a}\) and not b and c ; == z <= a and (not b) and c ; == z <= c and ( a and (not b));
\(y<=a\) and not \((b\) and \(c)\); -- \(z=1\) kun for \(a=1, b=0, c=1 . \quad y=1\) for \(a=1\) og (b eller \(c)=0\).

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\section*{VHDL operator priority}

\section*{Examples:}
```

x <= a or b and c; == x <= (a or b) and c;

```

(What you might want)

\[
\begin{aligned}
& \text { Try } \\
& \mathrm{a}:=\mathrm{r}, \\
& \mathrm{~b}:=1 \text { ' } \\
& \mathrm{c}:=\mathrm{o}
\end{aligned}
\]
(what you actually will get)

\(z<=a\) and not \(b\) and \(c ;==z<=a\) and (not b) and \(c ;==z<=c\) and ( \(a\) and (not b)); \(\mathrm{y}<=\mathrm{a}\) and not ( b and c );


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\section*{Bit operators and reduction operator}
- and, or, not, xor, xnor operators will work at bit level when they are placed between two signals or vectors.
- y1 <= a and b; -- is equal to the lines below \(y 1(3)<=a(3)\) and \(b(3)\);
\(y 1(2)<=a(2)\) and \(b(2)\);
\(y 1(1)<=a(1)\) and \(b(1)\);
\(y 1(0)<=a(0)\) and \(b(0)\);
- I VHDL2008 (not earlier) these operators can be used for reduction
```

y <= and a ; -- is equal to the figure ->

```
- xor can be used this way to generate (even) parity for a signal.


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\section*{VHDL Bit String Literals}

\section*{Binary, Decimal, heXadecimal, Octal, Unsigned, Signed}
<ant bit><U/S><B/D/O/X><numbers of type B/D/O/X >
```

B"1111_1111_1111" -- Equivalent to the string literal
"111111111111". 12UB"X1" -- Equivalent to B"0000_0000_00X1"
X"FFF" -- Equivalent to B"1111_1111_1111". 12SB"X1" - - Equivalent to B"XXXX_XXXX_XXX1"
0"777" -- Equivalent to B"111_111_111".
X"777" -- Equivalent to B"0111_0111_0111".
B"XXXX_01LH" -- Equivalent to the string literal
"XXXX01LH"
UO"27" -- Equivalent to B"010_111"
UO"2X" -- Equivalent to B"011_XXX"
SX"3W" -- Equivalent to B"0011_WWWW"
D"35" -- Equivalent to B"100011"
12UX"F-" -- Equivalent to B"0000_1111_----"
12SX"F-" -- Equivalent to B"1111_1111_----"

```

12SB"X1" -- Equivalent to B"XXXX_XXXX_XXX1"
12UX"F-" -- Equivalent to B"0000_1111_----"
12SX"F-" -- Equivalent to B"1111_1111_----"
12D"13" -- Equivalent to B"0000_0000_1101"
12UX"000WWW" -- Equivalent to B"WWWW_WWWW_WWWW"
12SX"FFFC00" -- Equivalent to B"1100_0000_0000"
12SX"XXXX00" -- Equivalent to B"XXXX_0000_0000"
8D"511" - Error (> 2^8)
8U0"477" - Error (>2^8)
8SX"0FF" - Error (cannot have 255 using 8 bit signed)
8SX"FXX" - Error (cannot extend beyond 8 bit)

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\section*{IN3160}

Code Layout (15 min)

Kilde: Ricardo Jasinski: Effective Coding with VHDL, Chapter 18

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\section*{Overview}
- Why bother thinking about layout?
- What constitutes a good layout scheme?
- Basic layout types
- Indentation
- Paragraphs and spaces

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\section*{Why bother thinking of layout?}
```

pRoCeSS(clock,reset) bEGIn iF resET then oUTpuT <="0000"; elSE IF RISING_edge
(ClOck) tHEN cASE s Is When 1=>outPUT<= "0001"; wHEn 2046=> oUTpuT <="0010";WheN
31=>OutPut<="0100"; when OTHERs=>OUTput <= <1111"; end CASe; END if; END proCESS; --
Q.E.D.

```

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\section*{A good layout scheme...}
1. ...accurately matches the structure of the code
2. ...improves readability
3. ...affords changes
4. ...is consistent (few exceptions)
5. ...is simple (few rules)
6. ...is easy to use
7. ...is economic

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\section*{Basic layout types}

Block layout


Endline layout


Column layout


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\section*{Block layout (What you should use most of the time)}
- Accurately matches structure
- relatively tidy
- readable,
- easy to maintain, etc.
```

process (clock, reset)
begin
if reset then
output <= "0000";
else if rising_edge(clock) then
case s is
when 1 => output <= "0001";
when 2046 => output <= "0010";
when 31 => output <= "0100;
when others => output <= "1111";
end case;
end if;
end process;

```

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\section*{Endline layout (avoid this)}
- Harder to maintain when code changes.
- Looks tidier, but isn't faster than pure block
- Will get messy- poor match of code hierarchy
- Long lines..!
```

process (clock, reset)
begin
if reset then output <= "0000";
else if rising_edge(clock) then case s is
when 1 => output <= "0001";
when 2046 => output <= "0010";
when 31 => output <= "0100";
when others => output <= "1111";
end case;
end if;
end process;

```

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\section*{Column layout (use sparingly)}
- Can be easier to read than pure block layout (scanning vertically)
- Harder to maintain.
- Best to use when columns are unlikely to change, and statements are related.
- Typically used for 2D arrays.
```

process (clock, reset)
begin
if reset then
output <= "0000";
else if rising_edge(clock) then
case s is
when 1 => output <= "0001";
when 2 => output <= "0010";
when 333 => output <= "0100";
when others => output <= "1111";
end case;
end if;
end process;

```

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\section*{Indentation}
- Use indentation to match code hierarchy
- 2-4 spaces has been proven most efficient
- Along with a monospace font, such as courier, consolas..
- Use space rather than tabulator sign.
- Tabulator spaces may be interpreted differently in different editors.
- Most editors can be set up for this.
- Example:
```

entity ent_name is
generic (
generic_declaration_1;
generic_declaration_2;
);
port(
port_declaration_1;
port_declaration_2;
);
end entity ent_name;
-
.
process (sensitivity_list)
declaration_1;
declaration_2;
begin
statement_1;
statement_2;
end process;

```

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\section*{Paragraphs and comments}
- Paragraphs should be used to separate chunks that does not need to be read all at once.
- Paired with comments that this make for good readability
- Comments should be indented as according to the code it is referring to.
```

-- Find character in text RAM corresponding to x, y
text_ram_x := pixel_x / FONT_WIDTH;
text_ram_y := pixel_y / FONT_HEIGHT;
display_char := text_ram(text_ram_x, text_ram_y);
-- Get character bitmap from ROM
ascii_code := character'pos(display_char);
char_bitmap := FONT_ROM(ascii_code);
-- Get pixel value from character bitmap
x_offset := pixel_x mod FONT_WIDTH;
y_offset := pixel_y mod FONT_HEIGHT;
pixel := char_bitmap(x_offset)(y_offset);

```

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\section*{Line length and wrapping}
- Try to keep line length within reasonable limits
- 80, 100 and 120 characters is widely used.
- When wrapping lines:
- break at a point that clearly shows it is incomplete, such as
- after opening paranthesis
- after operators or commas (\& +, -, *, /)
- after keywords such as «and» or «or»
- consider one item per line...
```

-- one item/line + named association
Paddle <= update_sprite(
sprite => paddle,
sprite_x => paddle_position.x + paddle_increment.x,
sprite_y => paddle_position.x + paddle_increment.y,
raster_x => vga_raster_x,
raster_y => vga_raster_y,
sprite_enabled => true
);

```
```

-- several items/line
paddle <= update_sprite(paddle, paddle_position.x + paddle_increment.y,
paddle_position.y + paddle_increment.y, vga_raster_x, vga_raster_y, true);

```

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\section*{Spaces}
- Punctuation symbols (comma, colon, semicolon)
```

-- too much
function add ( addend : signed ; augend : signed ) return signed ;
-- better
function add(addend: signed; augend: signed) return signed;

```
- use spaces as you would in regular prose:
- Never add space before punctuation symbols
- Always add space after punctuation symbols
- no exceptions
- Parantheses
- Add a space before opening paranthesis.
- Add a space or punctuation symbol after closing paranthesis
- Except:
- array indices and routine parameters;
- expressions.
```

-- consider this expression:
a + b mod c sll d;
-- better
(a + (b mod c)) sll d;

```
```

-- consider

```
-- consider
(-b+sqrt(b**2-4*a*c))/2*a;
(-b+sqrt(b**2-4*a*c))/2*a;
-- better
-- better
(-b + sqrt(b**2 - 4*a*c)) / 2*a;
(-b + sqrt(b**2 - 4*a*c)) / 2*a;
-- too much
-- too much
( - b + sqrt( b ** 2-4*a*c ) ) / 2*a;
```

( - b + sqrt( b ** 2-4*a*c ) ) / 2*a;

```

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\section*{Naming conventions - Letter case and underscores}
- Do not use ALL_CAPS too frequently.
- Use editor colors/ bold for higlighting keywords
- Try to avoid mixing snakes_andCamels.
- Treat acronyms/ abbreviations as words
- "UDPHDRFromIPPacket" vs
"UdpHdrFromIpPacket" vs
"udp_hdr_from_ip_packet"
- VHDL packages tend to favour snake_case and ALL_CAPS
- Suggestion:
- Use snake_case for all names except constants and generics that use ALL_CAPS

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\section*{Suggested reading, Mandatory assignments}
- D\&H:
- 1.5 p 13-16
- 3.6 p 51-54
- 6.1 p 105-106
- Oblig 1: «Design Flow»
- Oblig 2: «VHDL»
- See canvas for further instruction.
(Layout is lecture only)```

