ESC-205

C++ for Embedded C Programmers

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Abstract

The C++ programming language is a superset of C. C++ offers additional support for object-oriented and generic programming while enhancing C's ability to stay close to the hardware. Thus, C++ should be a natural choice for programming embedded systems. Unfortunately, many potential users are wary of C++ because of its alleged complexity and hidden costs.

This session explains the key features that distinguish C++ from C. It sorts the real problems from the imagined ones and recommends low-risk strategies for adopting C++. Rather than tell you that C++ is right for you, this session will help you decide for yourself.

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Dan Saks

Dan Saks is the president of Saks & Associates, which offers training and consulting in C and C++ and their use in developing embedded systems.

Dan writes the "Programming Pointers" column for *embedded.com* online. He has written columns for several other publications including *The C/C++ Users Journal, The C++ Report, Embedded Systems Design,* and *Software Development.* With Thomas Plum, he wrote *C++ Programming Guidelines,* which won a *1992 Computer Language Magazine Productivity Award.*

Dan served as secretary of the ANSI and ISO C++ Standards committees and as a member of the ANSI C Standards committee. More recently, he contributed to the *CERT Secure C Coding Standard* and the *CERT Secure C++ Coding Standard*.

Dan is also a Microsoft MVP.

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The "++" in C++

- C++ is a programming language based on the C language.
- Like C, C++ is a general-purpose language.
 - It's not targeted toward any particular application domain.
- C++ retains C's ability to deal efficiently with bits and bytes.
- C++ is particularly useful for embedded systems programming.

The "++" in C++ C++ extends C with features that support large-scale programming. These features help you organize large programs into smaller, simpler units. Compared to C, C++ lets you draw boundaries between subunits:

- more clearly
- more reliably
- no less efficiently (and sometimes even more efficiently)

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The "++" in C++

- One way to simplify building large systems is to build them from libraries of components:
 - functions
 - objects
 - types
- You can produce better software in less time by:
 - using components that others have written and tested, and
 - returning the favor.
 - That is, when feasible, package parts of your application(s) as components to share.
- C++ offers rich features for building libraries of components.

The "++" in C++ C++ provides better support for large-scale development: object-oriented programming classes class derivation (inheritance) virtual functions (polymorphism) generic programming templates global name management namespaces C++11 (the current Standard) provides better support for low-level programming.

Saying "Hello"

• Here's the classic "Hello, world" program in Standard C:

```
// "Hello, world" in Standard C
```

#include <stdio.h>

}

```
int main() {
    printf("Hello, world\n");
    return 0;
```

• This is also a Standard C++ program.

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```
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```







User-Defined Types

• In C, you might represent clock times as:

```
struct clock_time {
    unsigned char hrs, mins, secs;
};
~~~
struct clock time t;
```

- That is, you'd invent a data type called clock_time and declare variables of that type representing clock times.
- A type such as clock_time is a *user-defined type*.
 - The *user* is you, the programmer.

















Classes

- C doesn't really have facilities for defining truly abstract types.
- C++ provides a general mechanism, *classes*, for specifying new types that are truly abstract.
- Classes are the essential feature that distinguishes C++ from C.





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```

Contrasting C with C++

- The following example illustrates basic class concepts in C++.
- It does so by contrasting a fairly traditional procedure-oriented C program with an object-oriented C++ program.
- The example program is called *xr*.
 - It's a simple cross-reference generator.
 - Posed as exercise 6-3 in Kernighan and Ritchie [1988].
 - Solved by Tondo and Gimpel [1989].







































- Suppose you later changed the program to use a different data structure, say a hash table.
- This interface, particularly names using the word tree, would be inappropriate, if not downright confusing.
- Again, this evidence that the cross-reference table is implemented as a tree adds conceptual complexity to main.
- Fortunately, that complexity is avoidable...

Encapsulating with Classes

- *xr* should be organized so that the implementation of the cross-reference table is completely hidden from the main function.
- ✓ Encapsulate design decisions inside classes.
- You can define a cross_reference_table class that encapsulates the data representation and functionality of a cross-reference table.
- Then implement *xr* using that class...

Encapsulating with Classes

• The class definition should look something like...

```
class cross_reference_table {
public:
    cross_reference_table();
    void insert(char const *w, int ln);
    void put();
private:
    struct tnode;
    tnode *root;
};
```

```
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```



Class Concepts

• A class can also contain function declarations:

```
class cross_reference_table {
public:
    cross_reference_table();
    void insert(char const *w, int Ln);
    void put();
private:
    struct tnode;
    tnode *root;
};
```

```
exactly class contain constant and type declarations.
    A class can also contain constant and type declarations.
    This class contains a type declaration:
    class cross_reference_table {
    public:
        cross_reference_table();
        void insert(char const *w, int ln);
        void put();
    private:
        struct tnode;
        tnode *root;
    };
```

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Access Specifiers

- The public class members are:
 - the *interface* to the services that a class provides to its users.
 - accessible everywhere in the program that the class is visible.
- The private class members are:
 - the *implementation details* behind the class interface.
 - accessible only to other members of the same class.
 - (This last statement is oversimplified, but sufficient for now.)



```
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```



main Before

```
• Here's the main function as it was originally:
int main() {
    int linenum = 1;
    tnode *root = NULL;
    char word[MAXWORD];
    while (getword(word, MAXWORD) != EOF)
        if (isalpha(word[0]))
            root = addtreex(root, word, Linenum);
        else if (word[0] == '\n')
            ++linenum;
    treexprint(root);
    return 0;
}
```



Encapsulation Support

- The cross_reference_table class:
 - completely hides the table implementation from main, and
 - prevents future maintainers from inadvertently violating the table abstraction.
- Using inline functions avoids adding any run-time cost.

Encapsulation Support

- C programmers typically implement abstract types using some combination of:
 - incomplete types
 - separate compilation
 - internal linkage (via the keyword static)
- In C, you get to choose your poison:
 - poor compiler enforcement of the abstraction
 - · loss of performance because you can't use inlining
 - excessively restrictive storage management policies
- For example...





A Ring Buffer

- In effect, the head and tail chase each other around the array.
- Initially, the head and tail have the same value, indicating an empty ring buffer.
- As the tail pulls away from the head, the buffer fills up.
- If the tail gets so far ahead that it wraps around and catches up to the head, the buffer will be full.
- As the head catches up to the tail, the buffer empties.
- When the head completely overtakes the tail, the buffer is empty once again.

A Ring Buffer "Class" in C

- You can implement the ring buffer "class" in C as:
 - a structure, with
 - associated functions.
- You can try to pretend that it's an abstract type, but you get no help from the compiler.
- The data members are all "public"...

```
A Ring Buffer "Class" in C
// ring_buffer.h - a ring buffer in C
enum { rb_size = 32 };
typedef struct ring_buffer ring_buffer;
struct ring_buffer {
    char array[rb_size];    // "public"
    sig_atomic_t head, tail;    // "public"
    ;;
inline void rb_init(ring_buffer *rb) {
    rb->head = rb->tail = 0;
}
~~~
```

```
// ring_buffer.h - a ring buffer in C (continued)
inline bool rb_empty(ring_buffer const *b) {
   return b->head == b->tail;
}
inline char rb_front(ring_buffer const *b) {
   return b->buffer[b->head];
}
inline void rb_pop_front(ring_buffer *b) {
   if (++b->head >= rb_size)
        b->head = 0;
}
void rb_push_back(ring_buffer *b, char c);
```





Using Incomplete Types // ring_buffer.h - a ring buffer in C typedef struct ring_buffer ring_buffer; // incomplete inline void rb_init(ring_buffer *rb) { rb->head = rb->tail = 0; // won't compile } ~~~ • You have to: • Move the definition for rb_init from the header to the source file, and... • Remove the keyword inline from its declaration.



A Ring Buffer Class in C++

```
// ring_buffer.h - a ring buffer in C++
~~~
class ring_buffer {
public:
    ring_buffer();
    bool empty() const;
    char &front();
    void pop_front();
    void push_back(char c);
private:
    enum { size = 32 };
    char array[size];
    sig_atomic_t head, tail;
};
```

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```
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```

```
A Ring Buffer Class Template
// ring_buffer.h - a ring buffer class template
template <sig atomic t N, typename element type>
class ring buffer {
public:
    ring_buffer();
   bool empty() const;
   element_type &front();
   void pop_front();
   void push back(c);
private:
   enum { size = N };
   element_type array[size];
    sig_atomic_t head, tail;
};
                                                        76
```





Device Registers			
 A UART is a "Universal Asynchronous Receiver/Transmitter". The example assumes the system supports two UARTs. The UART 0 group consists of six device registers: 			
Offset 0xD000 0xD004 0xD008 0xD00C 0xD010 0xD014 • The UART 0xE000	Register ULCON UCON USTAT UTXBUF URXBUF UBRDIV	<u>Description</u> line control register control register status register transmit buffer register receive buffer register baud rate divisor register	ŧ
0			79





- Normally, you don't choose the memory locations where program objects reside.
 - The compiler does, often with substantial help from the linker.
- For an object representing memory-mapped device registers:
 - The compiler doesn't get to choose where the object resides.
 - The hardware has already chosen.
- Thus, to access a memory-mapped object:
 - The code needs some way to reference the location as if it were an object of the appropriate type...

Pointer-Placement

- In C++, as in C, you can use *pointer-placement*.
- That is, you cast the integer value of the device register address into a pointer value:

- The device register has a fixed location.
- The pointer to that location should be **const**.
 - Its value never changes.

Placing Memory-Mapped Objects

 Once you've got the pointer initialized, you can manipulate the device register via the pointer, as in:

```
*UTXBUF0 = c; // OK: send the value of c out the port
```

 This writes the value of character c to the UART 0's transmit buffer, sending the character value out the port.





UART Operations Many UART operations involve more than one UART register. For example: The TBE bit (Transmit Buffer Empty) is the bit masked by 0x40 in the USTAT register. The TBE bit indicates whether the UTXBUF register is ready for use. You shouldn't store a character into UTXBUF until the TBE bit is set to 1. Storing a character into UTXBUF initiates output to the port and clears the TBE bit. The TBE bit goes back to 1 when the output operation completes.



A UART Structure in C

• Here's a C function that sends characters from a null-terminated character sequence to any UART:

```
void put(UART *u, char const *s) {
   for (; *s != '\0'; ++s) {
      while ((u->USTAT & TBE) == 0)
      ;
      u->UTXBUF = *s;
   }
}
```

```
A UART Class in C++
• A C++ class can package the UART as a better abstraction:
  class UART {
  public:
               // see the next few slides
      \sim \sim \sim
  private:
      device_register ULCON;
      device_register UCON;
      device_register USTAT;
      device_register UTXBUF;
      device_register URXBUF;
      device register UBRDIV;
      enum { RDR = 0x20, TBE = 0x40 };
      \sim \sim \sim
  };
```

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A UART Class in C++

• These public members are for controlling transmission speed: class UART { public: $\sim \sim \sim$ enum baud rate { BR_9600 = 162 << 4, BR_19200 = 80 << 4, ~~~ }; void set speed(baud rate br) { UBRDIV = br; } ~~~~ }; set_speed is defined, not just declared, within its class definition. • As such, it's implicitly an inline function.





The class has two constructors:



A UART Class in C++

 Here (again) is the C function that sends characters from a nullterminated character sequence to any UART:

```
void put(UART *u, char const *s) {
   for (; *s != '\0'; ++s) {
      while ((u->USTAT & TBE) == 0)
      ;
      u->UTXBUF = *s;
   }
}
```

<text><code-block></code>







- Reading from a write-only register also produces unpredictable misbehavior that can be hard to diagnose.
- Again, you're better off catching this at compile time, too.
- Unfortunately, C++ doesn't have a write-only qualifier.
- Neither does C.
- However, you can enforce write-only semantics by using a class template...

A Write-Only Class Template

- write_only<T> is a simple class template for write-only types.
- For any type T, a write_only<T> object is just like a T object, except that it doesn't allow any operations that read the object's value.
- For example,

```
write_only<int> m = 0;
write_only<int> n;
n = 42;
m = n; // compile error: attempts to read the value of n
```

A Write-Only Class Template

• The class template definition is:

```
template <typename T>
class write_only {
public:
    write_only(write_only const &) = delete;
    write_only &operator=(write_only const &) = delete;
    write_only() { }
    write_only(T const &v): m (v) { }
    void operator=(T const &v) { m = v; }
private:
    T m;
};
```



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A Read-Only Class Template

• The class template definition looks like:

```
template <typename T>
class read_only {
public:
    read_only(read_only const &) = delete;
    read_only &operator=(read_only const &) = delete;
    read_only() { }
    operator T const &() const { return m; }
    T const *operator&() const { return &m; }
private:
    T m;
};
```



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Common C++ Misinformation

- Claim: C++ features such as function overloading, friends, inheritance, namespaces, and virtual functions have an added run-time cost.
- Fact:
 - Function overloading, friends, and namespaces have no runtime cost.
 - Moreover, overloading supports compile-time algorithm selection, which leads to faster code.
 - Inheritance without virtual functions also has no cost.
 - Virtual functions have a slight cost, but:
 - It's no different from using function call dispatch tables in C.
 - You don't pay for it unless you ask for it explicitly.

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Common C++ Misinformation

- Claim: C supports encapsulation as well as C++ does.
- Fact:
 - Absolutely not (as explained earlier).





References and Other Readings

- Kernighan and Ritchie [1988]. Brian Kernighan and Dennis Ritchie. *The C Programming Language, 2nd. ed.* Prentice Hall.
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- Tondo and Gimpel [1989]. Clovis Tondo and Scott Gimpel, *The C Answer Book, 2nd. ed.* Prentice Hall.