# NumPy Primer

An introduction to numeric computing in Python

#### What is NumPy?

Numpy, SciPy and Matplotlib: MATLAB-like functionality for Python

Numpy:

Typed multi-dimensional arrays

Fast numerical computation

High-level mathematical functions

#### Why do we need NumPy?

Numeric computing in Python is slow.

1000 x 1000 matrix multiply

Triple loop: > 1000 seconds

NumPy: 0.0279 seconds

#### Overview

- 1. Arrays
- 2. Shaping and transposition
- 3. Mathematical operations
- 4. Indexing and slicing
- 5. Broadcasting

#### Arrays

```
import numpy as np
a = np.array([[1,2,3],[4,5,6]], dtype=np.float32)
print a.ndim, a.shape, a.dtype
```

- 1. Arrays can have any number of dimensions, including zero (a scalar).
- 2. Arrays are typed. Common dtypes are: np.uint8 (byte), np.int64 (signed 64-bit integer), np.float32 (single-precision float), np.float64 (double-precision float).
- 3. Arrays are dense. Each element of the array exists and has the same type.

## Arrays, creation

- 1. np.ones, np.zeros
- 2. np.arange
- 3. np.concatenate
- 4. np.astype
- 5. np.zeros\_like, np.ones\_like
- 6. np.random.random

#### Arrays, failure cases

- 1. Must be dense, no holes
- 2. Cannot mix type
- 3. Cannot combine arrays of different shape

## Shaping

```
a = a.reshape(3,2)
a = a.reshape(-1,2)
a = a.ravel()
```

- 1. Total number of elements cannot change
- 2. Use -1 on an axis to automatically infer shape
- 3. Note: default order is row-major, MATLAB is column-major

#### Return values

NumPy operations return views or copies.

Views share the underlying storage of the original array. Changing the values of a view will change the original and vice versa.

Read the documentation to determine if an operation returns a copy or a view. Most operations return a view when possible and a copy otherwise.

np.copy, np.view will make explicit copies and views.

#### Transposition

```
a = np.arange(10).reshape(5,2)
a = a.T
a = a.transpose((1,0))
```

np.transpose will permute axes.

Terminology: Most operations have an np and ndarray equivalent.

```
a = np.transpose(a, (1, 0))
```

## Saving and loading arrays

```
np.savez('data.npz', a=a)
data = np.load('data.npz')
a = data['a']
```

- 1. NPZ file can hold multiple arrays
- 2. np.savez\_compressed is an alternative

#### Image arrays

Images are 3D: width, height and channels (typically R, G, B)

Common image formats:

height x width x RGB (band-interleaved)

RGB x height x width (band-sequential)

Alternatives: Channel order may be RGB or BGR, spatial dimensions may be transposed (width x height).

#### Saving and loading images

SciPy: skimage.io.imread, skimage.io.imsave

height x width x RGB

PIL / Pillow: PIL.Image.open, Image.save

width x height x RGB

OpenCV2: cv2.imread, cv2.imwrite

height x width x BGR

#### Image Examples

```
# convert height x width x RGB -> RGB x height x width
I = I.transpose((2,0,1))
# collapsing spatial dimensions
I = I.reshape(3, -1)
# convert RGB <-> BGR
I = I[::-1]
```

#### Recap

We know how to create arrays, reshape them and permute their axes.

Next, math on arrays

#### Mathematical operations

Arithmetic operations (e.g., add, subtract, multiply, divide and power) are elementwise.

Logical operations (e.g., a<0) return an array with dtype np.bool. More on this later.

np.dot(a,b) or a.dot(b) to form the matrix product.

In-place operations modify the array

$$a = a + b$$

$$a += b$$

#### Math, upcasting

The result will have a dtype that is more general or precise when the operands have differing type.

Failure case: upcast will not occur to prevent underflow or overflow. You must manually upcast one of the operands first.

**Important note**: images are typically stored as uint8. You will want to convert images to float32 or float64 before doing math on them.

```
img = skimage.io.imread('foo.jpg')

I = img/255.0 # 255.0 is float so result will be upcast
```

#### Math, universal functions

Terminology: a universal function is called a ufunc

Like arithmetic, universal functions are element-wise.

Examples: np.exp, np.sqrt, np.sin, np.cos, np.isnan

#### Indexing

```
x[0,0] # top-left element
x[0,-1] # first row, last column
x[0] # first row
x[:,0] # first column
```

- 1. Indices are zero-based
- 2. Multi-dimensional indices are comma separated (i.e., a tuple)

## Indexing, slices and arrays

```
I[1:-1,1:-1]  # select all but one-pixel border
I = I[:,:,::-1]  # swap channel order
I[I<10] = 0  # set dark pixels to black
I[[1,3]]  # select 2nd and 4th row</pre>
```

- 1. A slice is a view, so you can write to it and the original array will be modified
- 2. Arrays can also be indexed by a list or another boolean array

#### Python slicing

```
Syntax: start:stop:step
```

```
a = list(range(10))
a[:3]  # indices 0, 1, 2
a[-3:]  # indices 7, 8, 9
a[3:8:2]  # indices 3, 5, 7
a[4:1:-1]  # indices 4, 3, 2 (this one is tricky)
```

#### Axes

```
a.sum()  # sum all entries

a.sum(axis=0)  # sum over rows

a.sum(axis=1)  # sum over columns

a.sum(axis=1, keepdims=True)
```

- 1. Use the axis parameter to control which axis NumPy operates on
- 2. Typically, the axis specified will disappear, keepdims keeps all dimensions

#### Broadcasting

a = a + 1 # add one to every element

When operating on multiple arrays, broadcasting rules are used.

Each dimension must match, from right-to-left

- 1. Dimensions of size 1 will broadcast (as if the value was repeated).
- 2. Otherwise, the dimension must have the same shape.
- 3. Extra dimensions of size 1 are added to the left as needed.

#### Broadcasting example

Suppose we want to add a color value to an image

a.shape is 100, 200, 3

b.shape is 3

a + b will pad b with two extra dimensions so it has an effective shape of  $1 \times 1 \times 3$ .

So, the addition will broadcast over the first and second dimensions.

#### Broadcasting failures

If a.shape is 100, 200, 3 but b.shape is 4 then a + b will fail. The trailing dimensions must have the same shape (or be 1).

## Average image

Who is this?



#### Practice exercise (optional, not graded)

Compute the average image of faces.

- 1. Download Labeled Faces in the Wild dataset (google: LFW face dataset). Pick a face with at least 100 images.
- 2. Call numpy.zeros to create a 250 x 250 x 3 float64 tensor to hold the result
- 3. Read each image with skimage.io.imread, convert to float and accumulate
- 4. Write the averaged result with skimage.io.imsave