
xy_python_utils Documentation

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Python utilities by Ying Xiong.

Getting Started

Install prerequisites:

```
pip install -r requirements.txt
```

Install this package in development mode:

```
python setup.py develop
```

Run unit tests:

```
cd xy_python_utils
python -m unittest discover -p "*_test.py"
cd ..
```

Generate documentation:

```
cd docs
make html
cd ..
```

Image Utilities

Some utility functions to handle images.

```
image_utils.create_icon_mosaic (icons,      icon_shape=None,      border_size=1,      bor-
                                der_color=None,      empty_color=None,      mo-
                                saic_shape=None, mosaic_dtype=<Mock name='mock.float'
                                id='140275493000336'>)
```

Create a mosaic of image icons.

Parameters icons: a list of icons to be put together for mosaic.

Currently we require all icons to be multi-channel images of the same size.

icon_shape: the shape of icons in the output mosaic.

If not specified, use the shape of first image in *icons*.

border_size: the size of border.

border_color: the color of border, black if not specified.

empty_color: the color for empty cells, black if not specified.

mosaic_shape: the shape of output mosaic.

If not specified, try to make a square mosaic according to number of icons.

mosaic_dtype: the 'dtype' of output mosaic.

Returns The created mosaic image.

```
image_utils.imresize (img, size)
```

Resize the input image.

Parameters img: the input image to be resized.

size: a scalar for 'scale' or a 2-tuple for '(num_rows, num_cols)'.

One of the *num_rows* or *num_cols* can be -1, which will be inferred such that the output image has the same aspect ratio as the input.

Returns The resized image.

Matplotlib Utilities

`matplotlib_utils.axes_equal_3d` (*ax=None*)

Mimic Matlab's *axis equal* command. The matplotlib's command `ax.set_aspect("equal")` only works for 2D plots, but not for 3D plots (those generated with `projection="3d"`).

Parameters *ax*: the axes whose x,y,z axis to be equalized.

If not specified, default to `plt.gca()`.

`matplotlib_utils.draw_with_fixed_lims` (*ax, draw_fcn*)

Save the *xlim* and *ylim* of *ax* before a drawing action, and restore them after the drawing. This is typically useful when one first does an *imshow* and then makes some annotation with *plot*, which will change the limits if not using this function.

`matplotlib_utils.imshowinfo` (*ax=None, image=None*)

Mimic Matlab's *imshowinfo* function that shows the image pixel information as the cursor swipes through the figure.

Parameters *ax*: the axes that tracks cursor movement and prints pixel information.

We require the *ax.images* list to be non-empty, and if more than one images present in that list, we examine the last (newest) one. If not specified, default to `plt.gca()`.

image: if specified, use this 'image's pixel instead of 'ax.images[-1]'s.

The replacement *image* must have the same dimension as *ax.images[-1]*, and we will still be using the *extent* of the latter when tracking cursor movement.

Returns None

`matplotlib_utils.imshow` (*volume, fps=20, ax=None*)

Play a sequence of image in *volume* as a video.

Parameters *volume*: the video volume to be played.

Its size can be either $M \times N \times K$ (for single-channel image per frame) or $M \times N \times C \times K$ (for multi-channel image per frame).

fps: the frame rate of the video.

ax: the axes in which the video to be played.

If not specified, default to `plt.gca()`.

`matplotlib_utils.imshow` (*ax, img, xlim=None, ylim=None, **kw*)

Enhance *ax.imshow* with coordinate limits.

Parameters *ax*: the axes in which an image will be drawn.

img: the 2D image to be drawn.

xlim, ylim: the horizontal coordinate limits of the image.

This will set the *extent* parameter of *ax.imshow*, which is relatively inconvenient to set directly because of the half-pixel issue. Default: (0, *num_cols*-1), (0, *num_rows*-1).

****kw:** other parameters to be passed to ‘*ax.imshow*’.

The *extent* will be ignored if presented.

Returns None

`matplotlib_utils.tight_subplot` (*num_rows*, *num_cols*, *plot_index*, *gap*=0.01, *marg_h*=0.01, *marg_w*=0.01, *fig*=None)

Add a tight subplot axis to the current (or a given) figure.

Parameters **num_rows:** number of rows.

num_cols: number of columns.

plot_index: the index to the subplot.

gap: the gap between axes, scalar or 2-tuple ‘(gap_h, gap_w)’.

Value should be between (0, 1).

marg_h: the margins in height, scalar or 2-tuple ‘(lower, upper)’.

Value should be between (0, 1).

marg_w: the margins in width, scalar or 2-tuple ‘(left, right)’.

Value should be between (0, 1).

fig: figure to which the new axes to be added to

Default to *plt.gcf()* if not specified.

Returns The newly added axes.

Numerical Differentiation

`numerical_differentiation.numerical_jacobian` (*fcn*, *x0*, *dx=1e-06*, *method=0*, *return_f0=False*)

Compute the numerical Jacobian matrix of a given function.

Parameters *fcn*: a function handle that takes an N-vector as input and return an M-vector.

x0: an input N-vector.

dx: a scalar for small change in *x0*.

method: a integer or string with following options:

- {0, 'forward'}: compute the Jacobian as $(f(x_0+dx)-f(x_0))/dx$.
- 1, 'central': compute the Jacobian as $(f(x_0+dx)-f(x_0-dx))/2/dx$.

return_f0: if set to true, also return *fcn(x0)*.

Returns *J*: the MxN Jacobian matrix.

f0: the function value at *x0*.

Examples

```
>>> J = numerical_jacobian(fcn, x0, ...)
>>> (J, f0) = numerical_jacobian(fcn, x0, ..., return_f0=True)
```

Numpy Utilities

Some extended utility functions for ‘numpy’ module.

`numpy_utils.meshgrid_nd(*arrs)`
Multi-dimensional meshgrid.

Parameters `x, y, z, ...: ndarray`

Multiple 1-D arrays representing the coordinates of the grid.

Returns `X, Y, Z, ...: ndarray`

Multi-dimensional arrays of shape $(\text{len}(x), \text{len}(y), \text{len}(z), \dots)$. Note that there is a discrepancy to the original 2D meshgrid, where the output array shape is swapped, i.e. $(\text{len}(y), \text{len}(x))$. Specifically, if:

```
X, Y = meshgrid(x, y)
X2, Y2 = meshgrid_nd(x, y)
```

then we have $X == X2.T$ and $Y == Y2.T$.

Examples

```
>>> X, Y, Z = np.meshgrid([1,2,3], [10,20], [-2,-3,-4,-5])
>>> X
array([[[1, 1, 1, 1],
        [1, 1, 1, 1]],
       [[2, 2, 2, 2],
        [2, 2, 2, 2]],
       [[3, 3, 3, 3],
        [3, 3, 3, 3]]])
>>> Y
array([[[10, 10, 10, 10],
        [20, 20, 20, 20]],
       [[10, 10, 10, 10],
        [20, 20, 20, 20]],
       [[10, 10, 10, 10],
        [20, 20, 20, 20]]])
>>> Z
array([[[ -2, -3, -4, -5],
        [-2, -3, -4, -5]],
       [[ -2, -3, -4, -5],
        [-2, -3, -4, -5]]])
```

```
[[ -2, -3, -4, -5],  
 [ -2, -3, -4, -5]])
```

`numpy_utils.null(A, tol=1e-12)`

Return the null space of matrix or vector A , such that:

$\text{dot}(A, \text{null}(A)) == \text{eps}(M, N)$

Each column r of $\text{null}(A)$ is a unit vector, and $\|\text{dot}(A, r)\| < \text{tol}$.

OS Utilities

Some extended utility functions for 'os' module.

`os_utils.cp_r(src, dst)`

Same effect as the unix command 'cp -r src dst', supporting the followings:

- 1.`cp_r("/path/to/src_file", "/path/to/dst_file")`: The 'src_file' is a single file, and 'dst_file' is created or overwritten if already exists.
- 2.`cp_r("/path/to/src_folder", "/path/to/dst_folder")`: The 'dst_folder' is a single folder, and 'dst_folder' will be created if not already exists, otherwise a "/path/to/dst_folder/src_folder" will be created.
- 3.`cp_r("/path/to/src", "/path/to/dst_folder")`: The 'src' can be either a file or a folder, and can contain wildcard characters (e.g. '*'), and the 'dst_folder' must already exist.
- 4.`cp_r(["/path/to/src1", "/path/to/src2", ...], "/path/to/dst_folder")`: The 'src' can be anything as the previous syntax, and the first argument can be either list or tuple. The 'dst_folder' must already exist.

`os_utils.mkdir_p(path[, mode=0o777])`

Create a leaf directory 'path' and all intermediate ones, and no error will be reported if the directory already exists. Same effect as the unix command 'mkdir -p path'.

`os_utils.rm_rf(path)`

Remove a file or a directory, recursively. No error will be reported if 'path' does not exist. The 'path' can be a list or tuple. Same effect as the unix command 'rm -rf path'.

Quaternion

Unittest Utilities

Utility functions for unit test.

`unittest_utils.check_gradient` (*fcn*, *dfcn*, *N*, *x0=None*, *dx=None*, *delta=0.0001*, *m=0.01*, *M=10*,
raise_exception=True)

Numerically check whether 'dfcn' calculates the gradient of 'fcn'.

More specifically, this function checks whether the following quantities are close to each other

- $f(x) - f(x_0)$
- $(x-x_0) \cdot f'(x_0)$

We consider them to be close enough if **either one** of the following is true

1. the absolute difference is smaller than $(m * \|x-x_0\|)$;
2. the relative difference is smaller than $(M * \|x-x_0\|)$.

Parameters fcn: a function handler with a single (vector or scalar) input and a scalar output.

dfcn: a function handler with a single (vector or scalar) input and a

vector output for gradient of 'fcn'. [NOTE]: Another option is to let `dfcn=None` (or something else that is not callable, e.g. `[]` or `True`), and `fcn` return a 2-tuple for both function value and its gradient.

N: the dimensionality of input to the function, which is a Nx1 vector.

x0: the initial input point evaluated by the function, with default

`{randn(N)}`.

dx, delta: the direction of evaluation point moves, such that::

$$x = x_0 + \text{delta} * dx$$

with 'dx' a unit Nx1 vector and 'delta' a scalar.

m, M: the thresholds described above.

`unittest_utils.check_jacobian` (*fcn*, *dfcn*, *N*, *x0=None*, *dx=None*, *delta=0.0001*, *m=0.01*, *M=10*,
raise_exception=True)

Numerically check whether 'dfcn' calculates the Jacobian of 'fcn'.

More specifically, whether the following vectors are close to each other

- $f(x) - f(x_0)$

• $J(x_0) \cdot (x - x_0)$

We consider them to be close enough if **either one** of the following is true

1. “absolutely” close with tolerance $m \cdot \|x - x_0\|$ (see ‘check_near_abs’);
2. “relatively” close with tolerance $M \cdot \|x - x_0\|$ (see ‘check_near_rel’).

Parameters **fcn**: a function handler with a single (vector or scalar) input and a

vector output.

dfcn: a function handler with a single (vector or scalar) input and a

matrix output for Jacobian of ‘fcn’. [NOTE]: Another option is to let dfcn=None (or something else that is not callable, e.g. [] or True), and fcn return a 2-tuple for both function value and its Jacobian.

The rest is the same as “check_gradient”.

`unittest_utils.check_near(v1, v2, tol, raise_exception=True)`

Check whether scalar/vector/matrix ‘v1’ and ‘v2’ are close to each other under tolerance tol, in the sense that:

```
(absolute)  ||v1 - v2|| <= tol,    **or**  
(relative)  ||v1 - v2|| / max(||v1||, ||v2||, eps) <= tol,
```

where $\| \cdot \|$ is the Frobenius norm.

`unittest_utils.check_near_abs(v1, v2, tol, raise_exception=True)`

Same as ‘check_near’ but only check in the “absolute” sense.

`unittest_utils.check_near_rel(v1, v2, tol, raise_exception=True)`

Same as ‘check_near’ but only check in the “relative” sense.

General Utilities

Some general utility classes and functions.

class `utils.Range` (*start*, *stop=None*, *step=None*)

A range of numbers from *start* (inclusive) to *end* (exclusive) with a given *step*. This class is similar to the *range* built-in in python3, but also supports floating point parameters.

Note the rounding effect when using floating point parameters. The suggested way is to pad an *epsilon* at the stop point:

```
Range(1.5, 1.8001, 0.3)  # 1.8 will be included.
Range(1.5, 1.7999, 0.3)  # 1.5 will be excluded.
Range(1.5, 1.8, 0.3)     # 1.8 should be excluded, but might not be
                          # because of rounding effect. Avoid this.
```

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