Jacob W. Crandall

Professor

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Research Interests

Artificial intelligence: Human-machine cooperation, robotics, machine learning, game theory

Appointments

1 1	
Sep 2021 – present	Brigham Young University, Provo, UT Professor, Computer Science Department
Aug 2016 – Aug 2021	Brigham Young University, Provo, UT Associate Professor, Computer Science Department
Jan 2013 – Aug 2016	Masdar Institute of Science and Technology, Abu Dhabi, UAE Associate Professor, Dept. of Electrical Engineering and Computer Science
Jul 2008 – Dec 2012	Masdar Institute of Science and Technology, Abu Dhabi, UAE Assistant Professor, Computing and Information Science Program
Nov 2009 – Nov 2011	Massachusetts Institute of Technology, Cambridge, MA Research Affiliate, Technology and Development Program
Jul 2008 – Jun 2009	Massachusetts Institute of Technology, Cambridge, MA Visiting Scholar, Technology and Development Program
Jan 2006 – Jun 2008	Massachusetts Institute of Technology, Cambridge, MA Postdoctoral Associate, Department of Aeronautics and Astronautics Supervisor: Prof. Mary L. Cummings, Humans and Automation Lab
Jun 2000 – Dec 2005	Brigham Young University, Provo, UT Research Assistant, Computer Science Department Advisor: Prof. Michael A. Goodrich, HCMI-MAGICC Lab

Education

Apr 2006	Brigham	Young	University,	Provo	UT
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Ph.D. in Computer Science

Dissertation: Learning Successful Strategies in Repeated General-Sum Games

Apr 2004 Brigham Young University, Provo, UT

M.S. in Computer Science

 $The sis: \ \textit{Towards Developing Effective Human-Robot Systems}$

Aug 2001 Brigham Young University, Provo, UT

B.S. in Computer Science (minor in Mathematics)

Publications

Designations:

- An <u>underlined name</u> indicates a students of whom I was the primary supervisor on the work
- An italicized name indicates a student I closely worked with on the work, but did not supervise
- * indicates corresponding author

High-Impact Publications

Includes papers that meet one or more of the following attributes:

- Journal articles and book chapters
- Papers published in top-tier conferences (acceptance rate < 30%)
- Papers published in conferences and workshops having 50+ citations (Google Scholar profile)
- Papers that received a best-paper award
- 1. T. Whiting, A. Gautam, J. Tye, M. Simmons, J. Henstrom, J. W. Crandall*. Confronting Barriers to Human-Robot Cooperation: Balancing Efficiency and Risk in Machine Behavior. iScience, Vol. 24, 101963, 2021.
- 2. J. W. Crandall*. When Autonomous Agents Model Other Agents: An Appeal for Altered Judgment Coupled with Mouths, Ears, and a Little More Tape. *Artificial Intelligence*, Vol. 280, 103219, 2020.
- 3. I. Rahwan*, **J. W. Crandall**, and J. F. Bonnefon. Intelligent Machines as Social Catalysts. *Proceedings of the National Academy of Sciences*, Vol. 117(114), pp. 7555-7557, 2020. (Invited commentary)
- 4. F. Ishowo-Oloko, J. F. Bonnefon, Z. Soroye, J. W. Crandall, I. Rahwan*, and T. Rahwan*. Behavioural evidence for a transparency-efficiency tradeoff in human-machine cooperation. Nature Machine Intelligence, Vol. 1, pp. 517-521, 2019.

 This article ranks in the top 0.25% for online attention (Altmetric)
- I. Rahwan*, M. Cebrian, N. Obradovich, J. Bongard, J. F. Bonnefon, C. Breazeal, J. W. Crandall, N. A. Christakis, I. D. Couzin, M. O. Jackson, N. R. Jennings, E. Kamar, I. M. Kloumann, H. Larochelle, D. Lazer, R. McElreath, A. Mislove, D. C. Parkes, A. Pentland, M. E. Roberts, A. Shariff, J. B. Tenenbaum, and M. Wellman. Machine Behaviour. *Nature*, Vol. 568, pp. 477-486, 2019.

Journal Impact Factor: 43.070; This article ranks in the top 0.05% for online attention (Altmetric)

- J. W. Crandall*, M. Oudah, Tennom, F. Ishowo-Oloko, S. Abdallah, J. F. Bonnefon, M. Cebrian, A. Shariff, M. A. Goodrich, and I. Rahwan*. Cooperating with Machines. Nature Communications, Vol. 9(1), Article No. 233, 2018.
 - Journal Impact Factor: 12.353; This article ranks near the top 0.15% for online attention (Altmetric); 3rd most accessed article in Nature Communication's *Top 50: Physics* as of July 2019
- M. Oudah, T. Rahwan, T. Crandall, and J. W. Crandall*. How AI Wins Friends and Influences People in Repeated Games with Cheap Talk. Proceedings of the Thirty-Second Conference on Artificial Intelligence (AAAI), New Orleans, LA, Feb 2018.
 Acceptance rate: 25%
- 8. Z. Almahmoud, J. W. Crandall, K. Elbassioni, T. T. Nguyen*, and M. Roozbehani. Dynamic Pricing in Smart Grids Under Thresholding Policies. *IEEE Transactions on Smart Grid*, Vol. 10(3), pp. 3415-3429, 2019.

Journal Impact Factor: 6.645

- 9. W. Shen*, J. W. Crandall, K. Yan, and C. Lopes. Information Design in Crowdfunding under Thresholding Policies. In *Proceedings of the Seventeenth International Conference on Autonomous Agents and Multi-agent Systems (AAMAS)*, Stockholm, Sweden, Jul 2018.

 Acceptance rate: 25%
- 10. W. Shen, A. Al Khemeiri, A. Almehrzi, W. Al Enezi, I. Rahwan, and J. W. Crandall*. Regulating Highly Automated Robot Ecologies: Insights from Three User Studies. In *Proceedings of the Fifth International Conference on Human-Agent Interaction (HAI)*, Bielefeld, German, Oct 2017.

Best Student Paper Award; Acceptance rate: 47%

- 11. S. V. Albrecht*, J. W. Crandall, and S. Ramamoorthy. Belief and Truth in Hypothesised Behaviors. Artificial Intelligence, Vol. 235, pp. 63-94, 2016.

 Journal Impact Factor: 4.797
- W. Shen*, C. V. Lopes, and J. W. Crandall. An Online Mechanism for Ridsharing in Autonomous Mobility-on-Demand Systems. In *Proceedings of the International Joint* Conference on Artificial Intelligence (IJCAI), New York City, NY, Jul 2016. Acceptance rate: 25%
- J. W. Crandall*. Robust Learning in Repeated Stochastic Games using Meta-Gaming. In Proceedings of the International Joint Conference on Artificial Intelligence (IJCAI), Buenos Aires, Argentina, Jul 2015.
 Acceptance rate: 29%
- 14. M. Oudah, V. Babushkin, T. Chenlinangjia, and J. W. Crandall*. Learning to Interact with a Human Partner. In *Proceedings of the Tenth ACM/IEEE International Conference on Human-Robot Interaction (HRI)*, Portland, OR, Mar 2015.

 Acceptance rate: 25%
- 15. S. V. Albrecht*, J. W. Crandall, and S. Ramamoorthy. An Empirical Study on the Practical Impact of Prior Beliefs over Policy Types. In *Proceedings of the Twenty-Ninth Conference on Artificial Intelligence (AAAI)*, Austin, TX, Jan 2015.

 Acceptance rate: 27%
 - Note: S. V. Albrecht was a visiting Ph.D. student to my group from Univ. of Edinburgh (advised by S. Ramamoorthy)
- J. W. Crandall*. Towards Minimizing Disappointment in Repeated Games. Journal of Artificial Intelligence Research, Vol. 49, pp. 111-142, 2014.
 Journal Impact Factor: 2.284
- 17. <u>V. Manohar</u> and **J. W. Crandall***. Programming Robots to Express Emotions: Interaction Paradigms, Communication Modalities, and Context. *IEEE Transactions on Human-Machine Systems*, Vol. 44, No. 3, pp. 362-373, 2014.

 Journal Impact Factor: 2.493
- M. Elidrisi*, N. Johnson, M. Gini, and J. W. Crandall. Fast Adaptive Learning in Repeated Stochastic Games by Game Abstraction. In Proceedings of the Thirteenth International Conference on Autonomous Agents and Multi-agent Systems (AAMAS), Paris, France, May 2014.

Acceptance rate: 24%

M. A. Goodrich*, J. W. Crandall, and E. Barakova. Teleoperation and Beyond for Assistive Humanoid Robots. Reviews of Human Factors and Ergonomics (David Kaber, Ed.), Vol. 9, No. 1, pp. 175-226, 2013.

- 20. J. W. Crandall*. Just Add Pepper: Extending Learning Algorithms for Repeated Matrix Games to Repeated Markov Games. In Proceedings of the Eleventh International Conference on Autonomous Agents and Multi-agent Systems (AAMAS), Valencia, Spain, June 2012. Acceptance rate: 20%
- 21. <u>V. Harutyunyan</u>, <u>V. Manohar</u>, <u>I. Ghezehei</u>, and **J. W. Crandall***. Cognitive Telepresence in Human-Robot Interactions. *Journal of Human-Robot Interaction*, Vol. 1, No. 2, pp. 158-182, 2012.
- 22. **J. W. Crandall***, M. L. Cummings, M. Della Penna, and P. M. A. deJong. Computing the Effects of Operator Attention Allocation in Human Control of Multiple Robots. *IEEE Transactions on Systems, Man, and Cybernetics, Part A: Systems and Humans*, Vol. 41, No. 3, pp. 385-397, May 2011.
- 23. **J. W. Crandall*** and M. A. Goodrich. Learning to Compete, Cooperate, and Compromise Using Reinforcement Learning. *Machine Learning*, Vol. 82, No. 3, pp. 281-314, Mar 2011.

 Journal Impact Factor: 1.848
- 24. **J. W. Crandall***, <u>A. Ahmed</u>, and M. A. Goodrich. Learning in Repeated Games with Minimal Information: The Effects of Learning Bias. In *Proceedings of the Twenty-Fifth Conference on Artificial Intelligence (AAAI)*, San Francisco, CA, Aug 2011.

 Acceptance rate: 25%
- J. W. Crandall*, M. L. Cummings, and C. E. Nehme. A Predictive Model for Human– Unmanned Vehicle Systems. AIAA Journal of Aerospace Computing, Information, and Communication, Vol. 6, No. 11, pp. 585-603, Nov 2009.
- 26. C. E. Nehme, B. Mekdeci, J. W. Crandall, and M. L. Cummings*. The Impact of Heterogeneity on Operator Performance in Futuristic Unmanned Vehicle Systems. International C2 Journal, Special Issue: Representing Human Decision Making in Constructive Simulations for Analysis, Vol. 2, No. 2, Dec 2008.
- 27. J. W. Crandall* and M. L. Cummings. Identifying Predictive Metrics for Supervisory Control of Multiple Robots. *IEEE Transactions on Robotics*, Vol. 23, No. 5, pp. 942-951, Oct 2007.

Journal Impact Factor: 4.036

- 28. C. E. Nehme*, J. W. Crandall, and M. L. Cummings. An Operator Function Taxonomy for Unmanned Aerial Vehicle Missions. In *Proceedings of the 12th International Command and Control Research and Technology Symposium*, Newport, RI, Jun 2007.
- 29. **J. W. Crandall*** and M. L. Cummings. Developing Performance Metrics for the Supervisory Control of Multiple Robots. In *Proceedings of the Second ACM/IEEE International Conference on Human-Robot Interaction (HRI)*, Washington, DC, Mar 2007.

 Acceptance rate: 22%
- 30. M. A. Goodrich*, T. W. McLain, J. Anderson, J. Sun, and **J. W. Crandall**. Managing Autonomy in Robot Teams: Observations from Four Experiments. In *Proceedings of the Second ACM/IEEE International Conference on Human-Robot Interaction (HRI)*, Washington, DC, Mar 2007.

Acceptance rate: 22%

- 31. M. L. Cummings*, C. E. Nehme, and J. W. Crandall. Predicting Operator Capacity for Supervisory Control of Multiple UAVs. In *Innovations Intelligent Machines*, Vol. 70, Studies in Computational Intelligence, J. S. Chahl, L. C. Jain, A. Mizutani, and M. Sato-Ilic, Eds., pp. 11-36, 2007.
- 32. J. W. Crandall*, M. A. Goodrich, D. R. Olsen, and C. W. Nielsen. Validating Human-Robot Interaction Schemes in Multi-Tasking Environments. *IEEE Transactions on Systems*, Man, and Cybernetics, Part A: Systems and Humans, Vol. 35, No. 4, pp. 438-449, Jul 2005.
- 33. J. W. Crandall* and M. A. Goodrich. Learning to Compete, Compromise, and Cooperate in Repeated General-Sum Games. In *Proceedings of the Twenty-Second International Conference on Machine Learning (ICML)*, Bonn, Germany, Aug 2005.

 Acceptance rate: 27%
- 34. **J. W. Crandall** and M. A. Goodrich*. Characterizing Efficiency of Human-Robot Interaction: A Case Study of Shared-Control Teleoperation. In *Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems*, Lausanne, Switzerland, Oct 2002.
- 35. **J. W. Crandall** and M. A. Goodrich*. Experiments in Adjustable Autonomy. In *Proceedings of the IEEE International Conference on Systems, Man, and Cybernetics*, Tuscan, AZ, Oct 2001.
- 36. M. A. Goodrich*, D. R. Olsen, **J. W. Crandall**, and T. J. Palmer. Experiments in Adjustable Autonomy. In *Proceedings of the IJCAI Workshop on Autonomy, Delegation, and Control: Interaction with Autonomous Agents*, Aug 2001.

Other Refereed Publications

- 37. A. Gautam*, J. W. Crandall, and M. A. Goodrich. Self-assessment of Proficiency of Intelligent Systems: Challenges and Opportunities. *International Conference on Applied Human Factors and Ergonomics (AHFE)*, 2020.
- 38. N. Mathema*, M. A. Goodrich, and J. W. Crandall. Predicting Plans and Actions in Two-Player Repeated Games. AAAI 2020 Workshop on Plan, Activity, and Intent Recognition, New York, NY, 2020.
- 39. **J. W. Crandall*** and <u>H. Pham</u>. Cooperating in Long-term Relationships with Time-Varying Structure. *Proceedings of the 18th International Conference on Autonomous Agents and Multi-agent Systems (AAMAS)*, Montreal, Canada, 2019. (Short paper)

 Acceptance rate: 52%
- 40. <u>C. C. Ashcraft</u>, M. A. Goodrich, and **J. W. Crandall***. Moderating Operator Influence in Human-Swarm Systems. *Proceedings of the IEEE International Conference on Systems*, *Man, and Cybernetics (SMC)*, Bari, Italy, 2019
- 41. M. A. Goodrich*, **J. W. Crandall**, M. Oudah, and *N. Mathema*. Using Narrative to Enable Longitudinal Human-Robot Interactions, *Proceedings of the HRI2018 Workshop on Longitudinal Human-Robot Teaming*, Chicago, IL, 2018.
- 42. **J. W. Crandall***, N. Anderson, C. Ashcraft, H. Grosh, J. Henderson, J. McClellan, A. Ne-upane, and M. A. Goodrich. Human-Swarm Interaction as Shared Control: Achieving Flexible Fault-Tolerant Systems. In Proceedings of the International Conference on Engineering Psychology and Cognitive Ergonomics, Vancouver, CA, 2017.

- 43. S. V. Albrecht*, **J. W. Crandall**, and Subramanian Ramamoorthy. E-HBA: Using Action Policies for Expert Advice and Agent Typification. In *Proceedings of the AAAI-15 Workshop on Multiagent Interaction without Prior Coordination*, 2015.
- 44. **J. W. Crandall***. Learning in Real-Time in Repeated Games Using Experts. In *Proceedings* of the Twelfth International Conference on Autonomous Agents and Multi-agent Systems (AAMAS), Minneapolis, MN, 2013. (short paper)

 Acceptance rate: 44%
- 45. <u>Y. Hassan</u>* and **J. W. Crandall**. Genetic Algorithms in Repeated Matrix Games: The Effects of Algorithmic Modifications and Human Input with Various Associates. In *Proceedings of the IEEE Symposium on Intelligent Agents*, Singapore, 2013.
- 46. **J. W. Crandall***, <u>M. H. Altakrori</u>, and <u>Y. M. Hassan</u>. Learning by Demonstration in Repeated Stochastic Games. In *Proceedings of the Tenth International Conference on Autonomous Agents and Multi-agent Systems (AAMAS)*, Taipei, Taiwan, May 2011. (short paper)

Acceptance rate: 45%

- 47. M. A. Goodrich*, P. B. Sujit, B. Pendleton, J. W. Crandall, and J. Pinto. Toward Multi-Operator, Multi-Robot Teams: Human Interaction with Bio-Inspired Teams. In Proceedings of the Tenth International Conference on Autonomous Agents and Multi-agent Systems (AA-MAS), Taipei, Taiwan, May 2011. (short paper)
 Acceptance rate: 45%
- 48. **J. W. Crandall***, M. A. Goodrich, and L. Lin. Encoding Intelligent Agents for Uncertain, Unknown, and Dynamic Tasks: From Programming to Interactive Artificial Learning. In *Proceedings of the AAAI Spring Symposium on Agents that Learn from Human Teachers*, Palo Alto, CA, Mar 2009.
- 49. M. L. Cummings*, P. Pina, **J. W. Crandall**. A Metric Taxonomy for Supervisory Control of Unmanned Vehicles. In *Proceedings of AUVSI's Unmanned Systems North America*, San Diego, CA, Jun 2008.
- 50. P. Pina*, M. L. Cummings, J. W. Crandall, and M. Della Pena. Identifying Generalizable Metric Classes to Evaluate Human-Robot Teams. In Proceedings of the HRI Workshop on Metrics for Human-Robot Interaction, Amsterdam, The Netherlands, Mar 2008.
- 51. C. E. Nehme*, J. W. Crandall, and M. L. Cummings. Using Discrete-Event Simulation to Model Situational Awareness of Unmanned-Vehicle Operators. In *Proceedings of the ODU/VMASC Modeling, Simulation, and Gaming Student Capstone Conference*, Suffolk, VA, Apr 2008.
- 52. **J. W. Crandall*** and M. L. Cummings. Attention Allocation Efficiency in Human-UV Teams. In *Proceedings of the AIAA Infotech@Aerospace Conference and Exhibit*, Rohnert Park, May 2007.
- 53. **J. W. Crandall*** and M. A. Goodrich. Learning to Teach and Follow in Repeated Games. In *Proceedings of the AAAI Workshop on Multiagent Learning*, Pittsburgh, PA, Jul 2005.
- 54. **J. W. Crandall*** and M. A. Goodrich. Learning Near-Pareto Efficient Solutions With Minimal Knowledge Requirements Using Satisficing. In *Proceedings of the AAAI Fall Symposium on Artificial Multiagent Learning*, Washington, D.C., Oct 2004.

- 55. M. A. Goodrich*, E. R. Boer, J. W. Crandall, R. W. Ricks, and M. L. Quigley. Behavioral Entropy in Human-Robot Interaction. In *Proceedings of the Performance Metrics for Intelligent Systems Workshop (PERMIS)*, Gaithersburg, MD, Aug 2004.
- 56. J. W. Crandall* and M. A. Goodrich. Establishing Reputation Using Social Commitment in Repeated Games. In *Proceedings of the AAMAS Workshop on Learning and Evolution* in Agent Based Systems, New York City, NY, Jul 2004.
- 57. J. W. Crandall* and M. A. Goodrich. Multiagent Learning During On-Going Human-Machine Interactions: The Role of Reputation. In *Proceedings of the AAAI Spring Symposium on Interaction between Humans and Autonomous Systems over Extended Operation*, Palo Alto, CA, Mar 2004.
- 58. **J. W. Crandall*** and M. A. Goodrich. Measuring the Intelligence of a Robot and its Interface. In *Proceedings of the Performance Metrics for Intelligent Systems Workshop (PERMIS)*, Gaithersburg, MD, Sep 2003.
- 59. **J. W. Crandall***, C. W. Nielsen, and M. A. Goodrich. Towards Predicting Robot Team Performance. In *Proceedings of the IEEE International Conference on Systems, Man, and Cybernetics*, Washington, D.C., Sep 2003.
- 60. C. W. Nielsen*, M. A. Goodrich, and J. W. Crandall. Experiments in Human-Robot Teams. Multi-Robot Systems: From Swarms to Intelligent Automata, Vol. 2, Eds. Alan C. Shultz, Lynne E. Parker, Frank E. Schneider, Kluwer Academic Publishers. Washington, D.C., Mar 2003.
- 61. M. A. Goodrich*, **J. W. Crandall**, and J. R. Stimpson. Neglect Tolerant Teaming: Issues and Dilemmas. In *Proceedings of the AAAI Spring Symposium on Human Interaction with Autonomous Systems in Complex Environments*, Palo Alto, CA, Mar 2003.
- 62. **J. W. Crandall*** and M. A. Goodrich. Principles of Adjustable Interactions. In *Proceedings* of the AAAI Fall Symposium on Human-Robot Interactions, Cape Cod, MA, Nov 2002.

Theses

- 63. **J. W. Crandall**. Learning Successful Strategies in Repeated General-Sum Games. Ph.D. Dissertation, Brigham Young University, Dec 2005.
- 64. **J. W. Crandall**. Towards Developing Effective Human-Robot Systems. M.S. Thesis, Brigham Young University, Dec 2003.

Teaching

- Excellence in Teaching Award nominee, Masdar Institute: 2012, 2013, and 2015

Full Courses Taught

- CS235 Data Structures, BYU
 - Semesters taught: Summer 2004, Fall 2016, Fall 2017 (2 sections), Fall 2018 (2 sections), Fall 2019 (2 sections), Fall 2020 (4 sections)
 - Total students: 744
- CS470 Introduction to Artificial Intelligence, BYU
 - Semesters taught: Fall 2016, Fall 2017, Fall 2018, Fall 2019
 - Total students: 231
- CS501R Human Interaction with Artificial Intelligence, BYU
 - Semesters taught: Winter 2018
 - Total students: 11
- CS601R Social AI: Theories and Applications, BYU
 - Semesters taught: Winter 2019
 - Total students: 13
- CIS503 & CIS603 Multi-Agent Systems, Masdar Institute
 - Semesters taught: Fall 2010, Fall 2011, Fall 2012, Fall 2013, Fall 2014, Fall 2015
 - Total students: 135
- FDN 453 (CIS453) Mathematics for Computer Science, Masdar Institute
 - Semesters taught: Fall 2010, Fall 2011, Fall 2012, Fall 2014, Fall 2015
 - Total students: 26
- CIS606 Machine Learning, Masdar Institute (co-taught with Wei Lee Woon)
 - Semesters taught: Spring 2014
 - Total students: 11
- ITE502 Principles of Computer Systems Engineering, Masdar Institute
 - Semesters taught: Fall 2009
 - Total students: 17
- 16.499 Learning in Games, MIT
 - Semesters taught: Spring 2008
 - Total students: 18

Undergraduate Mentoring at BYU (Aug 2016-present)

Student	Dates	Student	Dates
Inoh Pak	Sep 2020 – present	Amber Theobald	Sep 2018 – Dec 2019
Lily Stice	Sep 2020 – present	Jordan Henstrom	Jan 2019 - Dec 2019
Paden Allsup	Sep 2020 - present	Elizabeth Van Patten	May 2018 – Aug 2019
Andrew Pulsipher	Jan 2018 – present	Chandler Clement	Jan 2018 - May 2019
Jessica Hamblin	May 2020 - present	Joshua McClellin	Sep 2016 - Apr 2018
Ethan Pedersen	Jan 2020 - Dec 2020	Nathan Anderson	Sep $2016 - Dec 2018$
Jacob Tye	Jan 2019 - Dec 2020	Jonathan Skaggs	May 2017 - Apr 2018
François Mahieu	Sep 2019 - Oct 2020	Trevin Avery	$Oct\ 2017 - Apr\ 2018$
Riley Parish	Jan 2020 – Aug 2020	Joshua Nelson	Jan 2018 - Apr 2018
Hazar Handal	$Jan\ 2020-Jun\ 2020$	Antonius Tolman	Jan 2018 - Apr 2018
Lee Woodside	$Jan\ 2020 - Apr\ 2020$	Danny Harding	May 2017 - Jun 2017
Sam Hopkins	Jan 2020 - Apr 2020	David Olsen	$Oct\ 2016 - Apr\ 2017$
Michael Simmons	May 2018 - Apr 2020	Justin Snyder	$Oct\ 2016 - Apr\ 2017$
Joshua Spencer	Jan 2018 - Dec 2019		

${\bf Graduate~Students~Supervised~(primary~advisor)}$

Student	Degree	Date	Topic
Joseph Johnson	PhD-BYU	Current	Modeling networks of agents/people
Jonathan Skaggs	PhD-BYU	Current	Machine learning
Tim Whiting	PhD-BYU	Current	Proficiency self-assessment
Michael Richards	MS-BYU	Current	Modeling networks of agents/people
Brian James	MS-BYU	Current	Machine learning
Huy Pham	MS-BYU	$\mathrm{Jun}\ 2020$	Learning in games
Chace Ashcraft	MS-BYU	$\mathrm{Apr}\ 2019$	Managing robot collectives
Mayada Oudah	PhD-MI	Aug 2017	How machines win friends and influence people
Wael Al-Enezi	MS-MI	Jul 2016	Cooperation in dynamic games
Tennom	MS-MI	$\mathrm{Jun}\ 2015$	Learning to cooperate with people
Abdulla Almehrzi	MS-MI	Sep 2014	Decision support for regulating machine societies
Alanoud Al Khemeiri	MS-MI	$\mathrm{Dec}\ 2014$	Regulating autonomous machine societies
Rafael Harutyunyan	MS-MI	July 2013	Modeling strategic social interactions
Wen Shen	MS-MI	May 2013	Regulating autonomous machine societies
Vahagn Harutyunyan	MS-MI	Aug 2012	Cognitive telepresence in human-robot systems
Malik Altakrori	MS-MI	Dec 2011	Learning from demonstrations in strategic interactions
Yomna Mahmoud	MS-MI	Aug 2011	Learning from demonstrations in strategic interactions
Edmond Awad	MS-MI	Aug 2011	Learning in transportation systems
Asad Ahmed	MS-MI	Aug 2011	Multi-agent learning
Mehmet Ergun	MS-MI	Jul 2011	Adaptation in new-age power systems
Salman Ahmed	MS-MI	Jun 2011	Distance metric learning from
Vimitha Manohar	MS-MI	May 2011	demonstration
viiiitiia Manonar	1112–1111	May 2011	Programming robots to express emotions

University Service

At BYU:

- 1. CS Undergraduate Committee (Jul 2020 present)
- 2. CS Expectations Committee (Jul 2020 present)
- 3. CS Teaching Committee (Jul 2020 present)
- 4. CS235 Curriculum Committee Chair (Aug 2017 present)
- 5. CS Colloquium Chair (Jul 2018 June 2020)
- 6. CS Faculty Search Committee (Aug 2019 Jun 2020)
- 7. CS CHI Council (Aug 2016 Jul 2018)
- 8. CS Department Undergraduate Committee (Aug 2016 Jul 2018)
- 9. CS Faculty Representative for the student ACM group (Aug 2016 Jul 2017)

At Masdar Institute:

- 1. EECS Faculty Recruitment and Advancement Committee (Nov 2015 Aug 2016)
- 2. Human Subjects Research Ethics Committee (Aug 2011 Aug 2016)
- 3. EECS Graduate Studies and Research Committee, Chair (Oct 2014 Oct 2015)
- 4. EECS Curriculum Committee (Oct 2013 Oct 2014)
- 5. CIS Program Effectiveness Committee (Feb 2013 Oct 2013)
- 6. CIS Program Accreditation Lead (June 2012 Sep 2013)
- 7. CIS Program Coordinator (Aug 2010 Aug 2011)
- 8. CIS Faculty Search Committee (Fall 2009 Sep 2013)
- 9. CIS Student MSc Admissions Committee (Jul 2008 Sep 2013)
- 10. PhD Admissions Committee (Spring 2011 Jun 2012)
- 11. Masdar Institute Seminar Series, Organizer (Fall 2010 Spring 2011)
- 12. Library Committee (Spring 2010 Aug 2010)
- 13. EE/EP Faculty Search Committee (Fall 2009 Spring 2010)

Academic Service

Associate Editor, ACM Transactions on Human-Robot Interaction, Dec 2017 – present Senior Editor, Journal of Human-Robot Interaction, June 2015 – Dec 2017 NSF Panelist (2017, 2018, 2019, 2020; 5 panels total + 2 external reviews)

Journal Reviewing

Nature; Nature Communications; IEEE Transactions on Systems, Man, and Cybernetics – Parts A and B; Journal of Economic Dynamics and Control; Machine Learning; IEEE Intelligent Systems; Human Factors; Artificial Intelligence; IEEE Transactions on Robotics; Journal of Aerospace Computing, Information, and Communication; Intelligent Service Robots; Journal of Artificial Intelligence Research; Autonomous Agents and Multi-agent Systems; Journal of Machine Learning Research; Automatica; Journal of Human-Robot Interaction; IEEE Transactions on Human-Machine Systems; International Journal of Social Robotics; Swarm Intelligence

Conference Organization and Reviewing

- The Joint International Conference on Artificial Intelligence (IJCAI)
 - Program Committee: 2007, 2009, 2011, 2016, 2017, 2019, 2020
 - Senior Program Committee: 2015
- The AAAI Conference on Artificial Intelligence (AAAI)
 - Senior Program Committee: 2018, 2019
 - Program Committee: 2007, 2014, 2015, 2016, 2017, 2020
 - Student Abstract Program Committee: 2007, 2008
- The International Conference on Autonomous Agents and Multiagent Systems (AAMAS)
 - Program Committee: 2006 2009, 2011, 2014
 - Senior Program Committee: 2013, 2016
- The International Conference on Machine Learning (ICML)
 - Program Committee: 2012 2014, 2020
- The International Conference on Human-Robot Interaction (HRI)
 - Program Committee: 2008 2020
 - Video Session Co-Chair: 2010, 2011
 - Publication Co-Chair: 2012, 2013
 - Registration Co-Chair: 2015
- Robotics: Science, and Systems Conference (RSS)
 - Program Committee: 2007, 2008, 2011, 2012
 - RSS Pioneers Program Committee: 2019
- The International Conference on Robotics and Automation (ICRA)
 - Program Committee: 2007, 2011 2014
- The International Conference on Intelligent Robots and Systems (IROS)
 - Program Committee: 2008
 - Associate Editor: 2011
- Neural Information Processing Systems (NeurIPS)
 - Area Chair: 2020
 - Program Committee: 2008, 2018, 2019
 - Given free NeurIPS 2018 registration for being one of the 218 highest-scoring reviewers
- Other
 - PCs: LAMAS 2005, RO-MAN 2008, ICAART 2010, SMC 2010, SRR 2010, SMC 2019
 - Workshop Organizer: MIPC 2014 and 2015 at AAAI
 - Publicity Co-Chair: PRIMA 2012

Grants Awarded

Date	Topic, PIs, and Funding Agency	Amount (\$)
2021 – 2022	Autonomous Robots for Proficiency Self-Assessment Funding Agency: Office of Naval Research (DURIP) PIs: J. W. Crandall and M. A. Goodrich	113,000
2018 – 2023	SUCCESS: Self-assessment and understanding of competence and conditions to ensure system success Funding Agency: Office of Naval Research (MURI) PIs: With 6 other PIs from Carnegie Mellon, BYU, Tufts, Univ. of Massachusetts, Lowell (I am lead PI at BYU)	BYU's Portion: 1,795,409
2016 – 2019	Leveraging the power of hub-based colonies: Flexibility and efficiency through human-swarm interfaces Funding agency: Army Research Lab PIs: J. W. Crandall and M. A. Goodrich	99,129
2013 – 2016	Information and decision architectures for future power grids Funding agency: MI-MIT Flagship Research Program PIs: With 7 other PIs from Masdar Institute and MIT (I was lead PI at MI) Note: 12.5% of proposals awarded	MI's Portion: 999,570
2012 – 2013	Managing real-time interventions in smart buildings Funding agency: Siemens PIs: J. Crandall and I. Rahwan Note: Discontinued (Dec 2012) due to restructuring within Siemens	261,913
2011 - 2012	Supervisory control of a humanoid robot Funding agency: Masdar Institute (internal research grant) PIs: J. Crandall, W. Woon, and H. Ghedira	100,000
2010	Agent modeling for carbon markets Funding agency: Monash-Masdar Seed Fund PIs: M. Chetti and J. Crandall	9,888
2009 – 2011	Intelligent devices for smart power grids Funding agency: MIT-Masdar Institute Collaborative Program PIs: J. Crandall and M. Dahleh	400,000